
SPIsHSPiSH

Release 2.8.2

Interactive Computer Graphics

Jun 17, 2020

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GETTING STARTED

This page should give you a short overview of SPlisHSPlasH.

SPlisHSPlasH currently consists of a simulators and different tools which are introduced in the following:

1.1 SPHSimulator

This application reads a SPlisHSPlasH scene file and performs a simulation of the scene.

The scene file format is explained [here](#).

1.1.1 Command line options:

- -h, --help: Print help text.
- --no-cache: Disable caching of boundary samples/maps.
- --state-file: Load a simulation state of the corresponding scene.
- --output-dir: Output directory for log file and partio files.
- --no-initial-pause: Disable caching of boundary samples/maps.
- --no-gui: Disable graphical user interface. The simulation is run only in the command line without graphical output. The “stopAt” option must be set in the scene file or by the next parameter.
- --stopAt arg: Sets or overwrites the stopAt parameter of the scene.
- --param arg: Sets or overwrites a parameter of the scene.
 - Setting a fluid parameter: ::
 - * Example: --param Fluid:viscosity:0.01
 - Setting a configuration parameter: :
 - * Example: --param cflMethod:1

1.1.2 Hotkeys

- Space: pause/continue simulation
- r: reset simulation
- w: wireframe rendering of meshes
- i: print all field information of the selected particles to the console
- s: save current simulation state
- l: load simulation state (currently only Windows)
- ESC: exit

1.2 Python bindings

SPlisHSPlasH implements bindings for python using `pybind11`. See the [getting started guide](#).

1.2.1 Impatient installation guide

In order to install, simply clone the repository and run pip install on the repository. It is recommended, that you set up a **virtual environment** for this, because cache files will be stored in the directory of the python installation along with models and scene files.

```
git clone https://github.com/InteractiveComputerGraphics/SPlisHSPlasH.git  
pip install SPlisHSPlasH/
```

1.3 Tools

1.4 partio2vtk

A tool to convert partio files in vtk files. In this way the particle data which is exported from SPlisHSPlasH can be converted to the vtk format. This is useful to import the data in ParaView for visualization.

1.5 PartioViewer

The simulators can export the particle simulation data using the partio file format. The PartioViewer can read such a file and render the particle data using OpenGL. This tool is able to handle multiphase data and rigid body data. It can create image sequences and movies (using ffmpeg).

To visualize a sequence of partio files or a single file, call (the index in the file name is used for the sequence):

```
PartioViewer fluid_data_1.bgeo
```

This tool is also able to read a complete output directory:

```
PartioViewer output/DamBreakModel
```

In this case the tool searches for the partio files of multiple phases in the subdirectory “partio” and for rigid body data in “rigid_bodies”.

Note: To generate videos you must tell PartioViewer where it can find the ffmpeg executable.

1.5.1 Command line options:

- -h, --help: Print help
- --renderSequence: Render a sequence from startFrame to endFrame as jpeg.
- --renderVideo: Render a sequence from startFrame to endFrame as video. This function requires ffmpeg which must be in the PATH or the ffmpegPath parameter must be set.
- --noOverwrite: Do not overwrite existing frames when using --renderSequence option. Existing frames are not loaded at all which accelerates the image sequence generation.
- -o, --outdir arg: Output directory for images
- --rbData arg: Rigid body data to visualize (bin file)
- --ffmpegPath arg: Path of the ffmpeg executable.
- --width arg: Width of the image in pixels. (default: 1024)
- --height arg: Height of the image in pixels. (default: 768)
- --fps arg: Frame rate of video. (default: 25)
- -r, --radius arg: Particle radius (default: 0.025)
- -s, --startFrame arg: Start frame (only used if value is ≥ 0) (default: -1)
- -e, --endFrame arg: End frame (only used if value is ≥ 0) (default: -1)
- --colorField arg: Name of field that is used for the color. (default: velocity)
- --colorMapType arg: Color map (0=None, 1=Jet, 2=Plasma) (default: 1)
- --renderMinValue arg: Min value of field. (default: 0.0)
- --renderMaxValue arg: Max value of field. (default: 10.0)
- --camPos arg: Camera position (e.g. --camPos “0 1 5”) (default: 0 3 10)
- --camLookat arg: Camera lookat (e.g. --camLookat “0 0 0”) (default: 0 0 0)

1.5.2 Hotkeys

- Space: pause/continue simulation
- r: reset simulation
- w: wireframe rendering of meshes
- i: print all field information of the selected particles to the console
- s: save current frame as jpg image
- v: generate video
- j: generate image sequence
- +: step to next frame
- -: step to previous frame

- ESC: exit

1.6 SurfaceSampling

A popular boundary handling method which is also implemented in SPlisHSPlasH uses a particle sampling of the surfaces of all boundary objects. This command line tool can generate such a surface sampling. Note that the same surface sampling is also integrated in the simulators and the samplings are generated automatically if they are required. However, if you want to generate a surface sampling manually, then you can use this tool.

1.7 VolumeSampling

The simulators can load particle data from partio files. This particle data then defines the initial configuration of the particles in the simulation. The VolumeSampling tool allows you to sample a volumetric object with particle data. This means you can load an OBJ file with a closed surface geometry and sample the interior with particles.

CHAPTER
TWO

SPLISHSPLASH SCENE FILES

A SPlisHSPlasH scene file is a json file which can contain the following blocks:

- Configuration
- FluidBlocks
- FluidModels
- Emitters
- RigidBodies
- Fluid parameter block
- Animation fields

2.1 Configuration

This part contains the general settings of the simulation and the pressure solver.

Example code:

```
"Configuration":  
{  
    "pause": true,  
    "sim2D": false,  
    "timeStepSize": 0.001,  
    "numberOfStepsPerRenderUpdate": 2,  
    "particleRadius": 0.025,  
    "simulationMethod": 4,  
    "gravitation": [0.0,-9.81,0],  
    "cflMethod": 1,  
    "cflFactor": 1,  
    "cflMaxTimeStepSize": 0.005,  
    "maxIterations": 100,  
    "maxError": 0.01,  
    "maxIterationsV": 100,  
    "maxErrorV": 0.1,  
    "stiffness": 50000,  
    "exponent": 7,  
    "velocityUpdateMethod": 0,  
    "enableDivergenceSolver": true  
}
```

2.1.1 General:

- pause (bool): Pause simulation at beginning.
- pauseAt (float): Pause simulation at the given time. When the value is negative, the simulation is not paused.
- stopAt (float): Stop simulation at the given time and exit. When the value is negative, the simulation is not stopped.
- cameraPosition (vec3): Initial position of the camera.
- cameraLookat (vec3): Lookat point of the camera.

2.1.2 Visualization:

- numberOfStepsPerRenderUpdate (int): Number of simulation steps per rendered frame
- renderWalls (int):
 - 0: None
 - 1: Particles (all)
 - 2: Particles (no walls)
 - 3: Geometry (all)
 - 4: Geometry (no walls)

2.1.3 Export

- enablePartioExport (bool): Enable/disable partio export (default: false).
- enableVTKExport (bool): Enable/disable VTK export (default: false).
- enableRigidBodyExport (bool): Enable/disable rigid body export (default: false).
- dataExportFPS (float): Frame rate of particle and rigid body export (default: 25).
- particleAttributes (string): A list of attribute names separated by ";" that should be exported in the particle files (e.g. "velocity;density") (default: "velocity").
- enableStateExport (bool): Enable/disable export of complete simulation state (default: false).
- stateExportFPS (float): Frame rate of simulation state export (default: 1).

2.1.4 Simulation:

- timeStepSize (float): The initial time step size used for the time integration. If you use an adaptive time stepping, this size will change during the simulation (default: 0.001).
- particleRadius (float): The radius of the particles in the simulation (all have the same radius) (default: 0.025).
- sim2D (bool): If this parameter is set to true, a 2D simulation is performed instead of a 3D simulation (default: false).
- enableZSort (bool): Enable z-sort to improve cache hits and therefore to improve the performance (default: true).
- gravitation (vec3): Vector to define the gravitational acceleration (default: [0,-9.81,0]).
- maxIterations (int): Maximal number of iterations of the pressure solver (default: 100).

- maxError (float): Maximal density error in percent which the pressure solver tolerates (default: 0.01).
- boundaryHandlingMethod (int): The boundary handling method that is used in the simulation (default: 2, Volume Maps):
 - 0: particle-based boundaries (Akinci et al. 2012)
 - 1: density maps (Koschier et al. 2017)
 - 2: volume maps (Bender et al. 2019)
- simulationMethod (int): The pressure solver method used in the simulation (default: 4, DFSPH):
 - 0: Weakly compressible SPH for free surface flows (WCSPH)
 - 1: Predictive-corrective incompressible SPH (PCISPH)
 - 2: Position based fluids (PBF)
 - 3: Implicit incompressible SPH (IISPH)
 - 4: Divergence-free smoothed particle hydrodynamics (DFSPH)
 - 5: Projective Fluids (dynamic boundaries not supported yet)

2.1.5 WCSPH parameters:

- stiffness (float): Stiffness coefficient of the equation of state.
- exponent (float): Exponent in the equation of state.

2.1.6 PBF parameters:

- velocityUpdateMethod (int):
 - 0: First Order Update
 - 1: Second Order Update

2.1.7 DFSPH parameters:

- enableDivergenceSolver (bool): Turn divergence solver on/off.
- maxIterationsV (int): Maximal number of iterations of the divergence solver.
- maxErrorV (float): Maximal divergence error in percent which the pressure solver tolerates.

2.1.8 Projective Fluids parameters:

- stiffness (float): Stiffness coefficient used by the pressure solver.

2.1.9 Kernel:

- kernel (int): Kernel function used in the SPH model.
 - For a 3D simulation:
 - * 0: Cubic spline
 - * 1: Wendland quintic C2
 - * 2: Poly6
 - * 3: Spiky
 - * 4: Precomputed cubic spline (faster than cubic spline)
 - For a 2D simulation:
 - * 0: Cubic spline
 - * 1: Wendland quintic C2
- gradKernel (int): Gradient of the kernel function used in the SPH model.
 - For a 3D simulation:
 - * 0: Cubic spline
 - * 1: Wendland quintic C2
 - * 2: Poly6
 - * 3: Spiky
 - * 4: Precomputed cubic spline (faster than cubic spline)
 - For a 2D simulation:
 - * 0: Cubic spline
 - * 1: Wendland quintic C2

2.1.10 CFL:

- cflMethod (int): CFL method used for adaptive time stepping.
 - 0: No adaptive time stepping
 - 1: Use CFL condition
 - 2: Use CFL condition and consider number of pressure solver iterations
- cflFactor (float): Factor to scale the CFL time step size.
- cflMinTimeStepSize (float): Min. allowed time step size.
- cflMaxTimeStepSize (float): Max. allowed time step size.

2.2 FluidBlocks

In this part the user can define multiple axis-aligned blocks of fluid particles.

Example code:

```
"FluidBlocks": [
    {
        "denseMode": 0,
        "start": [-2.0, 0.0, -1],
        "end": [-0.5, 1.5, 1],
        "translation": [1.0, 0.0, 0.0],
        "scale": [1, 1, 1]
    }
]
```

- start (vec3): Minimum coordinate of the box which defines the fluid block.
- end (vec3): Maximum coordinate of the box which defines the fluid block.
- translation (vec3): Translation vector of the block.
- scale (vec3): Scaling vector of the block.
- denseMode (int):
 - 0: regular sampling
 - 1: more dense sampling
 - 2: dense sampling
- initialVelocity (vec3): The initial velocity is set for all particles in the block.
- id (string): This id is used in the “Fluid parameter block” (see below) to define the properties of the fluid block. If no id is defined, then the standard id “Fluid” is used.

2.3 FluidModels

This part can be used to import one or more partio particle files in the scene.

Example code:

```
"FluidModels": [
    {
        "particleFile": "../models/bunny.bgeo",
        "translation": [-2.0, 0.1, 0.0],
        "rotationAxis": [0, 1, 0],
        "rotationAngle": 3.14159265359,
        "scale": 1
    }
]
```

- particleFile (string): Path of the partio file which contains the particle data.
- translation (vec3): Translation vector of the fluid model.
- scale (vec3): Scaling vector of the fluid model.
- rotationAxis (vec3): Axis used to rotate the particle data after loading.

- rotationAngle (float): Rotation angle for the initial rotation of the particle data.
- id: This id is used in the “Fluid parameter block” (see below) to define the properties of the fluid block. If no id is defined, then the standard id “Fluid” is used.

2.4 Emitters

In this part the user can define one or more emitters which generate fluid particles.

Example code:

```
"Emitters": [
    {
        "width": 5,
        "height": 5,
        "translation": [-1, 0.75, 0.0],
        "rotationAxis": [0, 1, 0],
        "rotationAngle": 3.1415926535897932384626433832795,
        "velocity": 2,
        "emitStartTime": 2,
        "emitEndTime": 6,
        "type": 0
    }
]
```

- type (int): Defines the shape of the emitter (default: 0).
 - 0: box
 - 1: circle
- width (int): Width of the box or radius of the circle emitter (default: 5).
- height (int): Height of the box (is only used for type 0) (default: 5).
- translation (vec3): Translation vector of the emitter (default: [0,0,0]).
- rotationAxis (vec3): Axis used to rotate the emitter. Note that in 2D simulations the axis is always set to [0,0,1] (default: [0,0,1]).
- rotationAngle (float): Rotation angle for the initial rotation of the emitter (default: 0).
- velocity (float): Initial velocity of the emitted particles in direction of the emitter (default: 1).
- id: This id is used in the “Fluid parameter block” (see below) to define the properties of the fluid block. If no id is defined, then the standard id “Fluid” is used (default: “Fluid”).
- emitStartTime (float): Start time of the emitter (default: 0).
- emitEndTime (float): End time of the emitter (default: REAL_MAX).

2.5 RigidBodies

Here, the static and dynamic rigid bodies are defined which define the boundary in the scene. In case of dynamic rigid bodies, the PositionBasedDynamics library is used for their simulation. Note that in this case the PositionBasedDynamics library also reads this json scene files and picks out the relevant parts. That means if you want to define for example a hinge joint or a motor, then just use the json format of PositionBasedDynamics in this scene file.

Example code:

```
"RigidBodies": [
    {
        "geometryFile": "../models/UnitBox.obj",
        "translation": [0,2,0],
        "rotationAxis": [1, 0, 0],
        "rotationAngle": 0,
        "scale": [2.5, 4, 1.0],
        "color": [0.1, 0.4, 0.6, 1.0],
        "isDynamic": false,
        "isWall": true,
        "mapInvert": true,
        "mapThickness": 0.0,
        "mapResolution": [20,20,20],
        "samplingMode": 1
    }
]
```

- geometryFile (string): Path to a OBJ file which contains the geometry of the body.
- particleFile (string): Path to a partio file which contains a surface sampling of the body. Note that the surface sampling is done automatically if this parameter is missing.
- translation (vec3): Translation vector of the rigid body.
- scale (vec3): Scaling vector of the rigid body.
- rotationAxis (vec3): Axis used to rotate the rigid body after loading.
- rotationAngle (float): Rotation angle for the initial rotation of the rigid body.
- isDynamic (bool): Defines if the body is static or dynamic.
- isWall (bool): Defines if this is a wall. Walls are typically not rendered. This is the only difference.
- color (vec4): RGBA color of the body.
- mapInvert (bool): Invert the map when using density or volume maps, flips inside/outside (default: false)
- mapThickness (float): Additional thickness of a volume or density map (default: 0.0)
- mapResolution (vec3): Resolution of a volume or density map (default: [20,20,20])
- samplingMode (int): Surface sampling mode. 0 Poisson disk sampling, 1 Regular triangle sampling (default: 0).

2.6 Materials

```
"Materials": [
    {
        "id": "Fluid",
        "density0": 1000,
        "colorField": "velocity",
        "colorMapType": 1,
        "renderMinValue": 0.0,
        "renderMaxValue": 5.0,
        "surfaceTension": 0.2,
        "surfaceTensionMethod": 0,
        "viscosity": 0.01,
        "viscosityMethod": 1,
        "vorticityMethod": 1,
        "vorticity": 0.15,
        "viscosityOmega": 0.05,
        "inertiaInverse": 0.5,
        "maxEmitterParticles": 1000,
        "emitterReuseParticles": false,
        "emitterBoxMin": [-4.0,-1.0,-4.0],
        "emitterBoxMax": [0.0,4,4.0]
    }
]
```

2.6.1 General

- id (string): Defines the id of the material. You have to give the same id to a FluidBlock, a FluidModel or an Emitter if they should have the defined material behavior.
- density0 (float): Rest density of the corresponding fluid.

2.6.2 Particle Coloring

- colorField (string): Choose vector or scalar field for particle coloring.
- colorMapType (int): Selection of a color map for coloring the scalar/vector field.
 - 0: None
 - 1: Jet
 - 2: Plasma
- renderMinValue (float): Minimal value used for color-coding the color field in the rendering process.
- renderMaxValue (float): Maximal value used for color-coding the color field in the rendering process.

2.6.3 Viscosity

- viscosityMethod (int): Viscosity method
 - 0: None
 - 1: Standard
 - 2: XSPH
 - 3: Bender and Koschier 2017
 - 4: Peer et al. 2015
 - 5: Peer et al. 2016
 - 6: Takahashi et al. 2015 (improved)
 - 7: Weiler et al. 2018
- viscosity (float): Coefficient for the viscosity force computation
- viscoMaxIter (int): (Implicit solvers) Max. iterations of the viscosity solver.
- viscoMaxError (float): (Implicit solvers) Max. error of the viscosity solver.
- viscoMaxIterOmega (int): (Peer et al. 2016) Max. iterations of the vorticity diffusion solver.
- viscoMaxErrorOmega (float): (Peer et al. 2016) Max. error of the vorticity diffusion solver.
- viscosityBoundary (float): (Weiler et al. 2018) Coefficient for the viscosity force computation at the boundary.

2.6.4 Vorticity

- vorticityMethod (int): Vorticity method
 - 0: None
 - 1: Micropolar model
 - 2: Vorticity confinement
- vorticity (float): Coefficient for the vorticity force computation
- viscosityOmega (float): (Micropolar model) Viscosity coefficient for the angular velocity field.
- inertiaInverse (float): (Micropolar model) Inverse microinertia used in the micropolar model.

2.6.5 Drag force

- dragMethod (int): Drag force method
 - 0: None
 - 1: Macklin et al. 2014
 - 2: Gissler et al. 2017
- drag (float): Coefficient for the drag force computation

2.6.6 Surface tension

- surfaceTensionMethod (int): Surface tension method
 - 0: None
 - 1: Becker & Teschner 2007
 - 2: Akinci et al. 2013
 - 3: He et al. 2014
- surfaceTension (float): Coefficient for the surface tension computation

2.6.7 Elasticity

- elasticityMethod (int): Elasticity method
 - 0: None
 - 1: Becker et al. 2009
 - 2: Peer et al. 2018
- youngsModulus (float): Young's modulus - coefficient for the stiffness of the material (default: 100000.0)
- poissonsRatio (float): Poisson's ratio - measure of the Poisson effect (default: 0.3)
- alpha (float): Coefficent for zero-energy modes suppression method (default: 0.0)
- elasticityMaxIter (float): (Peer et al. 2018) Maximum solver iterations (default: 100)
- elasticityMaxError (float): (Peer et al. 2019) Maximum elasticity error allowed by the solver (default: 1.0e-4)

2.6.8 Emitters

- maxEmitterParticles (int): Maximum number of particles the emitter generates. Note that reused particles (see below) are not counted here.
- emitterReuseParticles (bool): Reuse particles if they are outside of the bounding box defined by emitterBoxMin, emitterBoxMax
- emitterBoxMin (vec3): Minimum coordinates of an axis-aligned box (used in combination with emitterReuseParticles)
- emitterBoxMax (vec3): Maximum coordinates of an axis-aligned box (used in combination with emitterReuseParticles)

2.7 Animation fields

In this part the user can define one or more animation fields which animate fluid particles. The user can define math expressions for the components of the field quantity. The typical math terms like cos,sin,... can be used.

Available expression variables:

- t: Current time.
- dt: Current time step size.
- x, y, z: Position of the particle which is in the animation field.

- vx, vy, vz: Velocity of the particle which is in the animation field.
- valuex, valuey, valuez: Value of the field quantity of the particle which is in the animation field.

Example:

```
"particleField": "angular velocity",
"expression_x": "valuex + cos(2*t)"
```

This means that in each step we add $\cos(2*t)$ to the x-component of the angular velocity.

Example code:

```
"AnimationFields": [
  {
    "particleField": "velocity",
    "translation": [-0.5, -0.5, 0],
    "rotationAxis": [0, 0, 1],
    "rotationAngle": 0.0,
    "scale": [0.5, 0.25, 0.8],
    "shapeType": 0,
    "expression_x": "cos(2*t)*0.1",
    "expression_y": "",
    "expression_z": ""
  }
]
```

- shapeType (int): Defines the shape of the animation field (default: 0).
 - 0: box
 - 1: sphere
 - 2: cylinder
- particleField (string): Defines the field quantity that should be modified by the field (e.g. velocity, angular velocity, position) (default: velocity).
- translation (vec3): Translation vector of the animation field (default: [0,0,0]).
- rotationAxis (vec3): Axis used to rotate the animation field (default: [0,0,1]).
- rotationAngle (float): Rotation angle for the initial rotation of the animation field (default: 0).
- scale (vec3): Scaling vector of the animation field.
 - shapeType=0 (box): This vector defines the width, height, depth of the box.
 - shapeType=1 (sphere): The x-component of the vector defines the radius of the sphere. The other components are ignored.
 - shapeType=2 (cylinder): The x- and y-component of the vector defines the height and radius of the cylinder, respectively. The z-component is ignored.
- expression_x (string): Math expression for the x-component of the field quantity (default="").
- expression_y (string): Math expression for the y-component of the field quantity (default="").
- expression_z (string): Math expression for the z-component of the field quantity (default="").

PYSPLISHSPLASH

3.1 Python bindings for the SPPlisHSPlasH library

3.2 Requirements

Currently the generation of python bindings is only tested on

- Linux Debian, gcc 8.3, Python 3.7/3.8 (Anaconda), CMake 3.13
- Windows 10, Visual Studio 15/17/19, Python 3.7/3.8 (Anaconda), CMake 3.13

Note that the compiler, the python installation as well as cmake have to be available from the command line for the installation process to work. MacOS builds should work but have not been tested.

3.3 Installation

In order to install it is advised that you create a new virtual environment so that any faults during installation can not mess up your python installation. This is done as follows for

conda

```
conda create --name venv python=3.7
conda activate venv
```

virtualenv

```
python3 -m virtualenv venv --python=python3.7
source venv/bin/activate
```

Now you can clone the repository by

```
git clone https://github.com/InteractiveComputerGraphics/SPPlisHSPlasH.git
```

And finally you should be able to install SPPlisHSPlasH using pip. **The trailing slash is important** otherwise pip will try to download the package, which is not supported yet at least. Also note, that `pip install SPPlisHSPlasH` should be called from **one directory above** the cloned source directory and **not within** the directory itself.

```
pip install SPPlisHSPlasH/
```

While `pip install` is useful if SPPlisHSPlasH should only be installed once, for development purposes it might be more sensible to build differently. Change into the SPPlisHSPlasH directory and build a python wheel file as follows

```
cd SPlisHSPlasH
python setup.py bdist_wheel
pip install -I build/dist/*.whl
```

When building a new version of SPlisHSPlasH simply run these commands again and the installation will be updated. The compile times will be lower, because the build files from previous installations remain. If you are getting compile errors please try to compile the pysplishsplash target of the CMake project separately.

Now check your installation by running

```
python -c "import pysplishsplash"
```

Note: You may have to install numpy. Future releases may already contain numpy as a dependency.

```
pip install numpy
```

3.4 I want to see something very very quickly

If you're very impatient, just run the following command after installing

```
splash
```

You will be prompted to select a preconfigured scene file which will then be run in a User Interface. For more options and functionality run. The keybindings in the GUI are the same as for the regular SPlisHSPlasH version.

```
splash --help
```

3.5 Minimal working example

The following examples should work, if SPlisHSPlasH was installed correctly. If you want to load other scene files, be sure to place them into the SPlisHSPlasH data directory structure.

With GUI

```
import pysplishsplash as sph

def main():
    base = sph.Exec.SimulatorBase()
    base.init()
    gui = sph.GUI.Simulator_GUI_TweakBar(base)
    base.setGui(gui)
    base.run()

if __name__ == "__main__":
    main()
```

Without GUI

```
import pysplishsplash as sph

def main():
    base = sph.Exec.SimulatorBase()
```

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```

base.init(useGui=False)
base.setValueFloat(base.STOP_AT, 10.0) # Important to have the dot to denote a_
↪float
base.run()

if __name__ == "__main__":
    main()

```

Outputting the results to a specific directory without GUI

```

import pysplishsplash as sph
from pysplishsplash.Extras import Scenes
import os

def main():
    base = sph.Exec.SimulatorBase()
    output_dir = os.path.abspath("where/you/want/the/data")
    base.init(useGui=False, outputDir=output_dir, sceneFile=Scenes.DoubleDamBreak)
    base.setValueFloat(base.STOP_AT, 20.0) # Important to have the dot to denote a_
↪float
    base.setValueBool(base.VTK_EXPORT, True)
    # Uncomment the next line to set the output FPS value (must be float)
    # base.setValueFloat(base.DATA_EXPORT_FPS, 10000.)
    base.run()

if __name__ == "__main__":
    main()

```

3.6 SPHSimulator.py

If you want to start the simulator in the same way as the C++ version, just use the SPHSimulator.py in the examples directory.

3.7 Modifying other properties

The bindings cover most of the public interface of the SPlisHSPlasH library. As such, it is possible to change components of the simulation dynamically. In the following example, the second cube in the well known double dam break scenario is replaced with a slightly larger cube.

```

import pysplishsplash
import pysplishsplash.Utilities.SceneLoaderStructs as Scene

def main():
    base = pysplishsplash.Exec.SimulatorBase()
    args = base.init()
    gui = pysplishsplash.GUI.Simulator_GUI_TweakBar(base)
    base.setGui(gui)
    scene = base.getScene()
    add_block = Scene.FluidBlock('Fluid', Scene.Box([0.0, 0.0, 0.0], [1.0, 1.0, 1.0]),
↪ 0, [0.0, 0.0, 0.0])
    scene.fluidBlocks[1] = add_block # In Place construction not supported yet
    base.run()

```

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```
if __name__ == "__main__":
    main()
```

CREATING SCENES

4.1 Loading the empty scene

Right now the easiest way to create a custom scene without specifying a `Scene.json` file, is to load the predefined empty scene.

```
import pysplishsplash as sph
import pysplishsplash.Utilities.SceneLoaderStructs as Scenes

base = sph.Exec.SimulatorBase()
base.init(sceneFile=Scenes.Empty)
```

This scene will set the default simulation method to be DFSPH and some other default values, which can all be changed later on.

4.2 Recreating the double dam break scenario

In order to recreate the double dam break scenario, we need to add a bounding box as well as two fluid cubes. The bounding box can be added as follows

```
scene = base.getScene()
scene.boundaryModels.append(Scenes.BoundaryData(meshFile="..../models/UnitBox.obj",
    ↪ translation=[0., 3.0, 0.], scale=[4., 6., 4.], color=[0.1, 0.4, 0.5, 1.0],
    ↪ isWall=True, mapInvert=True, mapResolution=[25, 25, 25]))
```

The two fluid blocks can at the end be added using

```
scene.fluidBlocks.append(Scenes.FluidBlock(id='Fluid', box=Scenes.Box([-1.5, 0.0, -1.
    ↪ 5], [-0.5, 2.0, -0.5]), mode=0, initialVelocity=[0.0, 0.0, 0.0]))
scene.fluidBlocks.append(Scenes.FluidBlock(id='Fluid', box=Scenes.Box([0.5, 0.0, 0.5],
    ↪ [1.5, 2.0, 1.5]), mode=0, initialVelocity=[0.0, 0.0, 0.0]))
```

This will recreate a somewhat larger scene than the default double dam break

4.3 Putting it all together

The following shows a script detailing how to build and run a custom double dam break. Follow the instruction from before to activate/ deactivate the GUI.

```
import pysplishsplash as sph
import pysplishsplash.Utilities.SceneLoaderStructs as Scenes

def main():
    # Set up the simulator
    base = sph.Exec.SimulatorBase()
    base.init(useGui=True, sceneFile=sph.Extras.Scenes.Empty)

    # Create a tweak bar simulator
    gui = sph.GUI.Simulator_GUI_TweakBar(base)
    base.setGui(gui)

    # Get the scene and add objects
    scene = base.getScene()
    scene.boundaryModels.append(Scenes.BoundaryData(meshFile="../models/UnitBox.obj",
                                                    translation=[0., 3.0, 0.], scale=[4., 6., 4.], color=[0.1, 0.4, 0.5, 1.0],
                                                    isWall=True, mapInvert=True, mapResolution=[25, 25, 25]))
    scene.fluidBlocks.append(Scenes.FluidBlock(id='Fluid', box=Scenes.Box([-1.5, 0.0, -1.5], [-0.5, 2.0, -0.5]), mode=0, initialVelocity=[0.0, 0.0, 0.0]))
    scene.fluidBlocks.append(Scenes.FluidBlock(id='Fluid', box=Scenes.Box([0.5, 0.0, 0.5], [1.5, 2.0, 1.5]), mode=0, initialVelocity=[0.0, 0.0, 0.0]))

    # Run the GUI
    base.run()

if __name__ == "__main__":
    main()
```

4.4 Loading a scene from file

Loading a scene from a file is as simple as simply specifying a custom scene file in the init function. This must be an **absolute path!**

```
custom_scene = os.path.abspath("scene.json")
base.init(sceneFile=custom_scene)
```

If you want to use a gui to locate the scene file you may want to use tkinter

```
import tkinter as tk
from tkinter import filedialog

tk.Tk().withdraw() # Dont show main window
custom_scene = filedialog.askopenfilename()
base.init(sceneFile=custom_scene)
```

**CHAPTER
FIVE**

RESTRICTIONS

- When modifying simulation parameters this is the recommended structure, as modification will only work after `base.initSimulation()` has been called.

```
base.initSimulation()
sim = sph.Simulation.getCurrent()
sim.setValue...()
base.runSimulation()
base.cleanup()
```

- `setValue...()` and `getValue...()` functions cannot accept vectors as arguments yet

6.1 Class Hierarchy

6.2 File Hierarchy

6.3 Full API

6.3.1 Namespaces

Namespace @54

Namespace Eigen

Contents

- *Namespaces*

Namespaces

- *Namespace Eigen::internal*

Namespace Eigen::internal

Contents

- *Classes*

Classes

- *Template Struct generic_product_impl< MatrixReplacement, Rhs, SparseShape, DenseShape, GemvProduct >*
- *Template Struct traits< SPH::MatrixReplacement >*

Namespace GenParam

Namespace SPH

Contents

- *Classes*
- *Enums*
- *Variables*

Classes

- *Struct FieldDescription*
- *Struct PoissonDiskSampling::CellPosHasher*
- *Struct PoissonDiskSampling::HashEntry*
- *Struct PoissonDiskSampling::InitialPointInfo*
- *Class AdhesionKernel*
- *Class AnimationField*
- *Class AnimationFieldSystem*
- *Class BlockJacobiPreconditioner3D*
- *Class BoundaryModel*
- *Class BoundaryModel_Akinci2012*
- *Class BoundaryModel_Bender2019*
- *Class BoundaryModel_Koschier2017*
- *Class CohesionKernel*
- *Class CubicKernel*
- *Class CubicKernel2D*
- *Class DragBase*
- *Class DragForce_Gissler2017*
- *Class DragForce_Macklin2014*
- *Class Elasticity_Becker2009*
- *Class Elasticity_Peer2018*
- *Class ElasticityBase*

- *Class Emitter*
- *Class EmitterSystem*
- *Class FluidModel*
- *Class GaussQuadrature*
- *Class JacobiPreconditioner1D*
- *Class JacobiPreconditioner3D*
- *Class MathFunctions*
- *Class MatrixReplacement*
- *Class MicropolarModel_Bender2017*
- *Class NonPressureForceBase*
- *Class PoissonDiskSampling*
- *Class Poly6Kernel*
- *Template Class PrecomputedKernel*
- *Class RegularSampling2D*
- *Class RegularTriangleSampling*
- *Class RigidBodyObject*
- *Class SimpleQuadrature*
- *Class Simulation*
- *Class SimulationDataDFSPH*
- *Class SimulationDataIISPH*
- *Class SimulationDataPBF*
- *Class SimulationDataPCISPH*
- *Class SimulationDataPF*
- *Class SimulationDataWCSPH*
- *Class SpikyKernel*
- *Class StaticRigidBody*
- *Class SurfaceTension_Akinci2013*
- *Class SurfaceTension_Becker2007*
- *Class SurfaceTension_He2014*
- *Class SurfaceTensionBase*
- *Class TimeIntegration*
- *Class TimeManager*
- *Class TimeStep*
- *Class TimeStepDFSPH*
- *Class TimeStepIISPH*
- *Class TimeStepPBF*

- *Class TimeStepPCISPH*
- *Class TimeStepPF*
- *Class TimeStepWCSPH*
- *Class TriangleMesh*
- *Class Viscosity_Bender2017*
- *Class Viscosity_Peer2015*
- *Class Viscosity_Peer2016*
- *Class Viscosity_Standard*
- *Class Viscosity_Takahashi2015*
- *Class Viscosity_Weiler2018*
- *Class Viscosity_XSPH*
- *Class ViscosityBase*
- *Class VorticityBase*
- *Class VorticityConfinement*
- *Class WendlandQuinticC2Kernel*
- *Class WendlandQuinticC2Kernel2D*

Enums

- *Enum BoundaryHandlingMethods*
- *Enum DragMethods*
- *Enum ElasticityMethods*
- *Enum FieldType*
- *Enum ParticleState*
- *Enum SimulationMethods*
- *Enum SurfaceSamplingMode*
- *Enum SurfaceTensionMethods*
- *Enum ViscosityMethods*
- *Enum VorticityMethods*

Variables

- *Variable SPH::gaussian_abscissae_1*
- *Variable SPH::gaussian_n_1*
- *Variable SPH::gaussian_weights_1*

Namespace std**Namespace Utilities****Contents**

- *Classes*

Classes

- *Struct SceneLoader::AnimationFieldData*
- *Struct SceneLoader::BoundaryData*
- *Struct SceneLoader::Box*
- *Struct SceneLoader::EmitterData*
- *Struct SceneLoader::FluidBlock*
- *Struct SceneLoader::FluidData*
- *Struct SceneLoader::MaterialData*
- *Struct SceneLoader::Scene*
- *Class SceneLoader*
- *Class SDFFunctions*
- *Class VolumeSampling*
- *Class WindingNumbers*

6.3.2 Classes and Structs

Template Struct generic_product_impl< MatrixReplacement, Rhs, SparseShape, DenseShape, GemvProduct >

- Defined in file_SPlisHSPlasH_Utilsities_MatrixFreeSolver.h

Inheritance Relationships**Base Type**

- public generic_product_impl_base< MatrixReplacement, Rhs, generic_product_impl< MatrixReplacement, Rhs > >

Struct Documentation

```
template<typename Rhs>
struct Eigen::internal::generic_product_impl<MatrixReplacement, Rhs, SparseShape, DenseShape, GemvProduct>
    Implementation of the matrix-free matrix vector product
```

Public Types

```
typedef Product<MatrixReplacement, Rhs>::Scalar Scalar
```

Public Static Functions

```
template<typename Dest>
void scaleAndAddTo (Dest &dst, const MatrixReplacement &lhs, const Rhs &rhs, const Scalar &alpha)
```

Template Struct traits< SPH::MatrixReplacement >

- Defined in file_SPlisHSPlasH_Utilsities_MatrixFreeSolver.h

Inheritance Relationships

Base Type

- public Eigen::internal::traits< SystemMatrixType >

Struct Documentation

```
template<>
struct traits<SPH::MatrixReplacement> : public Eigen::internal::traits<SystemMatrixType>
```

Struct FieldDescription

- Defined in file_SPlisHSPlasH_FluidModel.h

Struct Documentation

```
struct SPH::FieldDescription
```

Public Functions

```
FieldDescription(const std::string &n, const FieldType &t, const
    std::function<void*> const unsigned int
    > &fct, const bool s = false)
```

Public Members

```
std::string name
FieldType type
std::function<void* (const unsigned int) getFct
bool storeData
```

Struct PoissonDiskSampling::CellPosHasher

- Defined in file_SPlisHSPlasH_Utilsities_PoissonDiskSampling.h

Nested Relationships

This struct is a nested type of *Class PoissonDiskSampling*.

Struct Documentation

```
struct SPH::PoissonDiskSampling::CellPosHasher
```

Public Functions

```
std::size_t operator() (const CellPos &k) const
```

Struct PoissonDiskSampling::HashEntry

- Defined in file_SPlisHSPlasH_Utilsities_PoissonDiskSampling.h

Nested Relationships

This struct is a nested type of *Class PoissonDiskSampling*.

Struct Documentation

struct SPH::*PoissonDiskSampling*::**HashEntry**
Struct to store the hash entry (spatial hashing)

Public Functions

HashEntry()

Public Members

std::vector<unsigned int> **samples**
unsigned int **startIndex**

Struct PoissonDiskSampling::InitialPointInfo

- Defined in file_SPlisHSPlasH_Utilsities_PoissonDiskSampling.h

Nested Relationships

This struct is a nested type of *Class PoissonDiskSampling*.

Struct Documentation

struct SPH::*PoissonDiskSampling*::**InitialPointInfo**
Struct to store the information of the initial points.

Public Members

CellPos **cP**
Vector3r **pos**
unsigned int **ID**

Struct SceneLoader::AnimationFieldData

- Defined in file_SPlisHSPlasH_Utilsities_SceneLoader.h

Nested Relationships

This struct is a nested type of [Class SceneLoader](#).

Struct Documentation

```
struct Utilities::SceneLoader::AnimationFieldData
    Struct to store an animation field object.
```

Public Members

```
std::string particleFieldName
std::string expression[3]
unsigned int shapeType
Vector3r x
Matrix3r rotation
Vector3r scale
Real startTime
Real endTime
```

Struct SceneLoader::BoundaryData

- Defined in file _SPlisHSPlasH_Utils_SceneLoader.h

Nested Relationships

This struct is a nested type of [Class SceneLoader](#).

Struct Documentation

```
struct Utilities::SceneLoader::BoundaryData
    Struct to store a boundary object.
```

Public Members

```
std::string samplesFile
std::string meshFile
Vector3r translation
Matrix3r rotation
Vector3r scale
Real density
bool dynamic
```

```
bool isWall
Eigen::Matrix<float, 4, 1, Eigen::DontAlign> color
void *rigidBody
std::string mapFile
bool mapInvert
Real mapThickness
Eigen::Matrix<unsigned int, 3, 1, Eigen::DontAlign> mapResolution
unsigned int samplingMode
```

Struct SceneLoader::Box

- Defined in file_SPlisHSPlasH_Utilsies_SceneLoader.h

Nested Relationships

This struct is a nested type of [Class SceneLoader](#).

Struct Documentation

```
struct Utilities::SceneLoader::Box
Struct for an AABB.
```

Public Members

```
Vector3r m_minX
Vector3r m_maxX
```

Struct SceneLoader::EmitterData

- Defined in file_SPlisHSPlasH_Utilsies_SceneLoader.h

Nested Relationships

This struct is a nested type of [Class SceneLoader](#).

Struct Documentation

struct Utilities::*SceneLoader*::**EmitterData**
 Struct to store an emitter object.

Public Members

```
std::string id
unsigned int width
unsigned int height
Vector3r x
Real velocity
Matrix3r rotation
Real emitStartTime
Real emitEndTime
unsigned int type
```

Struct SceneLoader::FluidBlock

- Defined in file_SPlisHSPlasH_Utils_SceneLoader.h

Nested Relationships

This struct is a nested type of *Class SceneLoader*.

Struct Documentation

struct Utilities::*SceneLoader*::**FluidBlock**
 Struct to store a fluid block.

Public Members

```
std::string id
Box box
unsigned char mode
Vector3r initialVelocity
```

Struct SceneLoader::FluidData

- Defined in file_SPlisHSPlasH_Utilsies_SceneLoader.h

Nested Relationships

This struct is a nested type of *Class SceneLoader*.

Struct Documentation

```
struct Utilities::SceneLoader::FluidData
    Struct to store a fluid object.
```

Public Members

```
std::string id
std::string samplesFile
Vector3r translation
Matrix3r rotation
Vector3r scale
Vector3r initialVelocity
unsigned char mode
bool invert
std::array<unsigned int, 3> resolutionSDF
```

Struct SceneLoader::MaterialData

- Defined in file_SPlisHSPlasH_Utilsies_SceneLoader.h

Nested Relationships

This struct is a nested type of *Class SceneLoader*.

Struct Documentation

```
struct Utilities::SceneLoader::MaterialData
    Struct to store particle coloring information.
```

Public Members

```
std::string id
std::string colorField
unsigned int colorMapType
Real minVal
Real maxVal
unsigned int maxEmitterParticles
bool emitterReuseParticles
Vector3r emitterBoxMin
Vector3r emitterBoxMax
```

Struct SceneLoader::Scene

- Defined in file_SPlisHSPlasH_Utilsies_SceneLoader.h

Nested Relationships

This struct is a nested type of *Class SceneLoader*.

Struct Documentation

```
struct Utilities::SceneLoader::Scene
Struct to store scene information.
```

Public Members

```
std::vector<BoundaryData*> boundaryModels
std::vector<FluidData*> fluidModels
std::vector<FluidBlock*> fluidBlocks
std::vector<EmitterData*> emitters
std::vector<AnimationFieldData*> animatedFields
std::vector<MaterialData*> materials
Real particleRadius
bool sim2D
Real timeStepSize
Vector3r camPosition
Vector3r camLookat
```

Class Matrix3f8

- Defined in file_SPlisHSPlasH_Utilsies_AVX_math.h

Class Documentation

```
class Matrix3f8
```

Public Functions

```
Matrix3f8()
Matrix3f8 (const Vector3f8 &m1, const Vector3f8 &m2, const Vector3f8 &m3)
void setZero()
Scalarf8 &operator() (int i, int j)
void setCol (int i, const Vector3f8 &v)
void setCol (int i, const Scalarf8 &x, const Scalarf8 &y, const Scalarf8 &z)
Matrix3f8 operator* (const Scalarf8 &b) const
Vector3f8 operator* (const Vector3f8 &b) const
Matrix3f8 operator* (const Matrix3f8 &b) const
Matrix3f8 &operator+=(const Matrix3f8 &a)
Matrix3f8 transpose() const
Scalarf8 determinant() const
void store (std::vector<Matrix3r> &Mf) const
Matrix3r reduce() const
```

Public Members

```
Scalarf8 m[3][3]
```

Class Quaternion8f

- Defined in file_SPlisHSPlasH_Utilsies_AVX_math.h

Class Documentation

```
class Quaternion8f
```

Public Functions

```
Quaternion8f()
Quaternion8f(Scalarf8 x, Scalarf8 y, Scalarf8 z, Scalarf8 w)
Quaternion8f(Vector3f8 &v)
Scalarf8 &operator[](int i)
Scalarf8 operator[](int i) const
Scalarf8 &x()
Scalarf8 &y()
Scalarf8 &z()
Scalarf8 &w()
Scalarf8 x() const
Scalarf8 y() const
Scalarf8 z() const
Scalarf8 w() const
const Quaternion8f operator*(const Quaternion8f &a) const
void toRotationMatrix(Matrix3f8 &R)
void toRotationMatrix(Vector3f8 &R1, Vector3f8 &R2, Vector3f8 &R3)
void store(std::vector<Quaternionr> &qf) const
void set(const std::vector<Quaternionr> &qf)
```

Public Members

Scalarf8 q[4]

Class Scalarf8

- Defined in file_SPlisHSPlasH_Utilsities_AVX_math.h

Class Documentation

```
class Scalarf8
```

Public Functions

```
Scalarf8()
Scalarf8 (float f)
Scalarf8 (Real f0, Real f1, Real f2, Real f3, Real f4, Real f5, Real f6, Real f7)
Scalarf8 (float const *p)
Scalarf8 (__m256 const &x)
Scalarf8 &operator= (__m256 const &x)
Scalarf8 sqrt () const
Scalarf8 rsqrt () const
Scalarf8 &load (float const *p)
void store (float *p) const
float reduce () const
```

Public Members

```
__m256 v
```

Class AdhesionKernel

- Defined in file_SPlisHSPlasH_SPHKernels.h

Class Documentation

```
class SPH::AdhesionKernel
Adhesion kernel used for the surface tension method of Akinci et al. [2].
```

Public Static Functions

```
Real getRadius ()
void setRadius (Real val)

Real W (const Real r)
W(r,h) = (0.007/h^3.25)(-4r^2/h + 6r -2h)^0.25 if h/2 < r <= h

Real W (const Vector3r &r)

Real W_zero ()
```

Protected Static Attributes

Real **m_radius**
Real **m_k**
Real **m_W_zero**

Class AnimationField

- Defined in file_SPlisHSPlasH_AnimationField.h

Class Documentation

```
class SPH::AnimationField
```

Public Functions

```
AnimationField(const std::string &particleFieldName, const Vector3r &pos, const Matrix3r
&rotation, const Vector3r &scale, const std::string expression[3], const un-
signed int type = 0)
~AnimationField()
void setStartTime (Real val)
void setEndTime (Real val)
void step ()
void reset ()
```

Protected Functions

```
FORCE_INLINE bool inBox (const Vector3r &x, const Vector3r &xBox, const Matrix3r &rotB
FORCE_INLINE bool inCylinder (const Vector3r &x, const Vector3r &xCyl, const Matrix3r &
FORCE_INLINE bool inSphere (const Vector3r &x, const Vector3r &pos, const Matrix3r &rot
FORCE_INLINE bool inShape (const int type, const Vector3r &x, const Vector3r &pos, con
```

Protected Attributes

std::string **m_particleFieldName**
Vector3r **m_x**
Matrix3r **m_rotation**
Vector3r **m_scale**
std::string **m_expression[3]**
unsigned int **m_type**
Real **m_startTime**
Real **m_endTime**

Class AnimationFieldSystem

- Defined in file_SPlisHSPlasH_AnimationFieldSystem.h

Class Documentation

```
class SPH::AnimationFieldSystem
```

Public Functions

```
AnimationFieldSystem()
~AnimationFieldSystem()

void addAnimationField(const std::string &particleFieldName, const Vector3r &pos, const
                      Matrix3r &rotation, const Vector3r &scale, const std::string expres-
                      sion[3], const unsigned int type)

unsigned int numAnimationFields() const
std::vector<AnimationField*> &getAnimationFields()

void step()
void reset()
```

Protected Attributes

```
std::vector<AnimationField*> m_fields
```

Class BlockJacobiPreconditioner3D

- Defined in file_SPlisHSPlasH_Utils_MatrixFreeSolver.h

Class Documentation

```
class SPH::BlockJacobiPreconditioner3D
Matrix-free 3x3 block Jacobi preconditioner
```

Public Types

```
enum [anonymous]
Values:
enumerator ColsAtCompileTime = Eigen::Dynamic
enumerator MaxColsAtCompileTime = Eigen::Dynamic
typedef SystemMatrixType::StorageIndex StorageIndex
typedef void (*DiagonalMatrixElementFct)(const unsigned int, Matrix3r&, void*)
```

Public Functions

```
BlockJacobiPreconditioner3D()
void init (const unsigned int dim, DiagonalMatrixElementFct fct, void *userData)
Eigen::Index rows () const
Eigen::Index cols () const
Eigen::ComputationInfo info ()
template<typename MatType>
BlockJacobiPreconditioner3D &analyzePattern (const MatType &)
template<typename MatType>
BlockJacobiPreconditioner3D &factorize (const MatType &mat)
template<typename MatType>
BlockJacobiPreconditioner3D &compute (const MatType &mat)
template<typename Rhs, typename Dest>
void _solve_impl (const Rhs &b, Dest &x) const
template<typename Rhs>
const Eigen::Solve<BlockJacobiPreconditioner3D, Rhs> solve (const Eigen::MatrixBase<Rhs> &b) const
```

Protected Attributes

```
unsigned int m_dim
DiagonalMatrixElementFct m_diagonalElementFct
    diagonal matrix element callback
void *m(userData
std::vector<Matrix3r> m_invDiag
```

Class BoundaryModel

- Defined in file_SPlisHSPlasH_BoundaryModel.h

Inheritance Relationships

Derived Types

- public SPH::BoundaryModel_Akinci2012 (*Class BoundaryModel_Akinci2012*)
- public SPH::BoundaryModel_Bender2019 (*Class BoundaryModel_Bender2019*)
- public SPH::BoundaryModel_Koschier2017 (*Class BoundaryModel_Koschier2017*)

Class Documentation

class SPH::BoundaryModel

The boundary model stores the information required for boundary handling.

Subclassed by *SPH::BoundaryModel_Akinci2012*, *SPH::BoundaryModel_Bender2019*,
SPH::BoundaryModel_Koschier2017

Public Functions

```
BoundaryModel()
~BoundaryModel()
void reset()
void performNeighborhoodSearchSort()
void saveState(BinaryFileWriter &binWriter)
void loadState(BinaryFileReader &binReader)
RigidBodyObject *getRigidBodyObject()
FORCE_INLINE void addForce (const Vector3r &pos, const Vector3r &f)
FORCE_INLINE void getPointVelocity (const Vector3r &x, Vector3r &res)
void getForceAndTorque (Vector3r &force, Vector3r &torque)
void clearForceAndTorque()
```

Protected Attributes

```
RigidBodyObject *m_rigidBody
std::vector<Vector3r> m_forcePerThread
std::vector<Vector3r> m_torquePerThread
```

Class BoundaryModel_Akinci2012

- Defined in file _SPlisHSPlasH_BoundaryModel_Akinci2012.h

Inheritance Relationships

Base Type

- public *SPH::BoundaryModel* (*Class BoundaryModel*)

Class Documentation

```
class SPH::BoundaryModel_Akinci2012 : public SPH::BoundaryModel
```

The boundary model stores the information required for boundary handling using the approach of Akinci et al. 2012 [1].

Public Functions

```
BoundaryModel_Akinci2012()
~BoundaryModel_Akinci2012()

unsigned int numberOfParticles() const
unsigned int getPointSetIndex() const
void computeBoundaryVolume()
void resize(const unsigned int numBoundaryParticles)
void reset()
void performNeighborhoodSearchSort()
void saveState(BinaryFileWriter &binWriter)
void loadState(Binary.FileReader &binReader)
void initModel(RigidBodyObject *rbo, const unsigned int numBoundaryParticles, Vector3r *boundaryParticles)
FORCE_INLINE Vector3r & getPosition0(const unsigned int i)
FORCE_INLINE const Vector3r & getPosition0(const unsigned int i) const
FORCE_INLINE void setPosition0(const unsigned int i, const Vector3r &pos)
FORCE_INLINE Vector3r & getPosition(const unsigned int i)
FORCE_INLINE const Vector3r & getPosition(const unsigned int i) const
FORCE_INLINE void setPosition(const unsigned int i, const Vector3r &pos)
FORCE_INLINE Vector3r & getVelocity(const unsigned int i)
FORCE_INLINE const Vector3r & getVelocity(const unsigned int i) const
FORCE_INLINE void setVelocity(const unsigned int i, const Vector3r &vel)
FORCE_INLINE const Real & getVolume(const unsigned int i) const
FORCE_INLINE Real & getVolume(const unsigned int i)
FORCE_INLINE void setVolume(const unsigned int i, const Real &val)
```

Protected Attributes

```
bool m_sorted
unsigned int m_pointSetIndex
std::vector<Vector3r> m_x0
std::vector<Vector3r> m_x
std::vector<Vector3r> m_v
std::vector<Real> m_V
```

Class BoundaryModel_Bender2019

- Defined in file_SPlisHSPlasH_BoundaryModel_Bender2019.h

Inheritance Relationships

Base Type

- public SPH::BoundaryModel (*Class BoundaryModel*)

Class Documentation

```
class SPH::BoundaryModel_Bender2019 : public SPH::BoundaryModel
```

The boundary model stores the information required for boundary handling using the approach of Bender et al. 2019 [10].

Public Functions

```
BoundaryModel_Bender2019()
~BoundaryModel_Bender2019()
void initModel (RigidBodyObject *rbo)
void reset ()
Discregrid::DiscreteGrid *getMap ()
void setMap (Discregrid::DiscreteGrid *map)
Real getMaxDist () const
void setMaxDist (Real val)
Real getMaxVel () const
void setMaxVel (Real val)
FORCE_INLINE const Real & getBoundaryVolume (const unsigned int fluidIndex, const unsigned int pointIndex)
FORCE_INLINE Real & getBoundaryVolume (const unsigned int fluidIndex, const unsigned int pointIndex)
FORCE_INLINE void setBoundaryVolume (const unsigned int fluidIndex, const unsigned int pointIndex, const Real val)
FORCE_INLINE Vector3r & getBoundaryXj (const unsigned int fluidIndex, const unsigned int pointIndex)
```

```
FORCE_INLINE const Vector3r & getBoundaryXj (const unsigned int fluidIndex, const unsigned int i, ...)
```

Protected Attributes

```
Discregrid::DiscreteGrid *m_map
std::vector<std::vector<Real>> m_boundaryVolume
std::vector<std::vector<Vector3r>> m_boundaryXj
Real m_maxDist
Real m_maxVel
```

Class BoundaryModel_Koschier2017

- Defined in file_SPlisHSPlasH_BoundaryModel_Koschier2017.h

Inheritance Relationships

Base Type

- public SPH::BoundaryModel (*Class BoundaryModel*)

Class Documentation

```
class SPH::BoundaryModel_Koschier2017 : public SPH::BoundaryModel
```

The boundary model stores the information required for boundary handling using the approach of Koschier and Bender 2017 [15].

Public Functions

```
BoundaryModel_Koschier2017()
~BoundaryModel_Koschier2017()
void initModel (RigidBodyObject *rbo)
void reset ()

Discregrid::DiscreteGrid *getMap ()
void setMap (Discregrid::DiscreteGrid *map)

Real getMaxDist () const
void setMaxDist (Real val)

Real getMaxVel () const
void setMaxVel (Real val)

FORCE_INLINE const Real & getBoundaryDensity (const unsigned int fluidIndex, const unsigned int i, ...)
```

```
FORCE_INLINE void setBoundaryDensity (const unsigned int fluidIndex, const unsigned int i, const unsigned int j, Real density)
FORCE_INLINE Vector3r & getBoundaryDensityGradient (const unsigned int fluidIndex, const unsigned int i, const unsigned int j, Vector3r & gradient)
FORCE_INLINE const Vector3r & getBoundaryDensityGradient (const unsigned int fluidIndex, const unsigned int i, const unsigned int j, const Vector3r & gradient)
FORCE_INLINE void setBoundaryDensityGradient (const unsigned int fluidIndex, const unsigned int i, const unsigned int j, const Real density)
FORCE_INLINE Vector3r & getBoundaryXj (const unsigned int fluidIndex, const unsigned int i, const unsigned int j, Vector3r & xj)
FORCE_INLINE const Vector3r & getBoundaryXj (const unsigned int fluidIndex, const unsigned int i, const unsigned int j, const Vector3r & xj)
FORCE_INLINE void setBoundaryXj (const unsigned int fluidIndex, const unsigned int i, const unsigned int j, const Vector3r & xj)
```

Protected Attributes

```
Discregrid::DiscreteGrid *m_map
std::vector<std::vector<Real>> m_boundaryDensity
std::vector<std::vector<Vector3r>> m_boundaryDensityGradient
std::vector<std::vector<Vector3r>> m_boundaryXj
Real m_maxDist
Real m_maxVel
```

Class CohesionKernel

- Defined in file_SPlisHSPlasH_SPHKernels.h

Class Documentation

```
class SPH::CohesionKernel
```

Cohesion kernel used for the surface tension method of Akinci et al. [2].

Public Static Functions

```
Real getRadius ()
void setRadius (Real val)
Real W (const Real r)
    W(r,h) = (32/(pi h^9))(h-r)^3*r^3 if h/2 < r <= h (32/(pi h^9))(2*(h-r)^3*r^3 - h^6/64 if 0 < r <= h/2
Real W (const Vector3r &r)
Real W_zero ()
```

Protected Static Attributes

Real **m_radius**

Real **m_k**

Real **m_c**

Real **m_W_zero**

Class CubicKernel

- Defined in file_SPlisHSPlasH_SPHKernels.h

Class Documentation

```
class SPH::CubicKernel
    Cubic spline kernel.
```

Public Static Functions

Real **getRadius ()**

void **setRadius (Real val)**

Real **W (const Real r)**

Real **W (const Vector3r &r)**

Vector3r **gradW (const Vector3r &r)**

Real **W_zero ()**

Protected Static Attributes

Real **m_radius**

Real **m_k**

Real **m_l**

Real **m_W_zero**

Class CubicKernel2D

- Defined in file_SPlisHSPlasH_SPHKernels.h

Class Documentation

```
class SPH::CubicKernel2D  
    Cubic spline kernel (2D).
```

Public Static Functions

```
Real getRadius ()  
void setRadius (Real val)  
Real W (const Real r)  
Real W (const Vector3r &r)  
Vector3r gradW (const Vector3r &r)  
Real W_zero ()
```

Protected Static Attributes

```
Real m_radius  
Real m_k  
Real m_l  
Real m_W_zero
```

Class DragBase

- Defined in file_SPlisHSPlasH_Drag_DragBase.h

Inheritance Relationships

Base Type

- public SPH::NonPressureForceBase (*Class NonPressureForceBase*)

Derived Types

- public SPH::DragForce_Gissler2017 (*Class DragForce_Gissler2017*)
- public SPH::DragForce_Macklin2014 (*Class DragForce_Macklin2014*)

Class Documentation

```
class SPH::DragBase : public SPH::NonPressureForceBase
    Base class for all drag force methods.
```

Subclassed by [SPH::DragForce_Gissler2017](#), [SPH::DragForce_Macklin2014](#)

Public Functions

```
DragBase (FluidModel *model)
~DragBase (void)
```

Public Static Attributes

```
int DRAG_COEFFICIENT = -1
```

Protected Functions

```
void initParameters ()
```

Protected Attributes

```
Real m_dragCoefficient
```

Class DragForce_Gissler2017

- Defined in file_SPlisHSPlasH_Drag_DragForce_Gissler2017.h

Inheritance Relationships

Base Type

- public SPH::DragBase (*Class DragBase*)

Class Documentation

```
class SPH::DragForce_Gissler2017 : public SPH::DragBase
    This class implements the drag force computation introduced by Gissler et al. [11].
```

Public Functions

```
DragForce_Gissler2017 (FluidModel *model)  
~DragForce_Gissler2017 (void)  
void step ()  
void reset ()
```

Protected Attributes

```
const Real rho_a = static_cast<Real>(1.2041)  
const Real sigma = static_cast<Real>(0.0724)  
const Real mu_1 = static_cast<Real>(0.00102)  
const Real C_F = static_cast<Real>(1.0 / 3.0)  
const Real C_k = static_cast<Real>(8.0)  
const Real C_d = static_cast<Real>(5.0)  
const Real C_b = static_cast<Real>(0.5)  
const Real mu_a = static_cast<Real>(0.00001845)
```

Class DragForce_Macklin2014

- Defined in file_SPlisHSPlasH_Drag_DragForce_Macklin2014.h

Inheritance Relationships

Base Type

- public SPH::DragBase (*Class DragBase*)

Class Documentation

```
class SPH::DragForce_Macklin2014 : public SPH::DragBase
```

This class implements the drag force computation introduced by Macklin et al. [18].

Public Functions

```
DragForce_Macklin2014 (FluidModel *model)  
~DragForce_Macklin2014 (void)  
void step ()  
void reset ()
```

Class Elasticity_Becker2009

- Defined in file_SPlisHSPlasH_Elasticity_Elasticity_Becker2009.h

Inheritance Relationships

Base Type

- public SPH::ElasticityBase (*Class ElasticityBase*)

Class Documentation

```
class SPH::Elasticity_Becker2009 : public SPH::ElasticityBase
```

This class implements the corotated SPH method for deformable solids introduced by Becker et al. [4].

Public Functions

```
Elasticity_Becker2009 (FluidModel *model)
~Elasticity_Becker2009 (void)
void step ()
void reset ()
void performNeighborhoodSearchSort ()
void saveState (BinaryFileWriter &binWriter)
void loadState (BinaryFileReader &binReader)
```

Public Static Attributes

```
int ALPHA = -1
```

Protected Functions

```
void initValues ()
void computeRotations ()
void computeStress ()
void computeForces ()
void initParameters ()
FORCE_INLINE void symMatTimesVec (const Vector6r &M, const Vector3r &v, Vector3r &res)
```

Protected Attributes

```
std::vector<unsigned int> m_current_to_initial_index
std::vector<unsigned int> m_initial_to_current_index
std::vector<std::vector<unsigned int>> m_initialNeighbors
std::vector<Real> m_restVolumes
std::vector<Matrix3r> m_rotations
std::vector<Vector6r> m_stress
std::vector<Matrix3r> m_F
Real m_alpha
```

Class Elasticity_Peer2018

- Defined in file_SPlisHSPlasH_Elasticity_Elasticity_Peer2018.h

Inheritance Relationships

Base Type

- public SPH::ElasticityBase (*Class ElasticityBase*)

Class Documentation

```
class SPH::Elasticity_Peer2018 : public SPH::ElasticityBase
```

This class implements the implicit SPH formulation for incompressible linearly elastic solids introduced by Peer et al. [21].

Public Functions

```
Elasticity_Peer2018 (FluidModel *model)
~Elasticity_Peer2018 (void)
void step ()
void reset ()
void performNeighborhoodSearchSort ()
void saveState (BinaryFileWriter &binWriter)
void loadState (BinaryFileReader &binReader)
```

Public Static Functions

```
void matrixVecProd(const Real *vec, Real *result, void *userData)
```

Public Static Attributes

```
int ITERATIONS = -1
int MAX_ITERATIONS = -1
int MAX_ERROR = -1
int ALPHA = -1
```

Protected Types

```
typedef Eigen::ConjugateGradient<MatrixReplacement, Eigen::Lower | Eigen::Upper, Eigen::IdentityPreconditioner> Solver
```

Protected Functions

```
void initValues()
void computeMatrixL()
void computeRotations()
void computeRHS(VectorXr &rhs)
void initParameters()
FORCE_INLINE void symMatTimesVec (const Vector6r &M, const Vector3r &v, Vector3r &res)
```

Protected Attributes

```
std::vector<unsigned int> m_current_to_initial_index
std::vector<unsigned int> m_initial_to_current_index
std::vector<std::vector<unsigned int>> m_initialNeighbors
std::vector<Real> m_restVolumes
std::vector<Matrix3r> m_rotations
std::vector<Vector6r> m_stress
std::vector<Matrix3r> m_L
std::vector<Matrix3r> m_RL
std::vector<Matrix3r> m_F
unsigned int m_iterations
unsigned int m_maxIter
Real m_maxError
Real m_alpha
Solver m_solver
```

Class ElasticityBase

- Defined in file_SPlisHSPlasH_Elasticity_ElasticityBase.h

Inheritance Relationships

Base Type

- public SPH::NonPressureForceBase (*Class NonPressureForceBase*)

Derived Types

- public SPH::Elasticity_Becker2009 (*Class Elasticity_Becker2009*)
- public SPH::Elasticity_Peer2018 (*Class Elasticity_Peer2018*)

Class Documentation

```
class SPH::ElasticityBase : public SPH::NonPressureForceBase
    Base class for all elasticity methods.
```

Subclassed by *SPH::Elasticity_Becker2009*, *SPH::Elasticity_Peer2018*

Public Functions

```
ElasticityBase (FluidModel *model)
~ElasticityBase (void)
```

Public Static Attributes

```
int YOUNGS_MODULUS = -1
int POISSON_RATIO = -1
```

Protected Functions

```
void initParameters ()
```

Protected Attributes

```
Real m_youngsModulus
Real m_poissonRatio
```

Class Emitter

- Defined in file_SPlisHSPlasH_Emitter.h

Class Documentation

```
class SPH::Emitter
```

Public Functions

```
Emitter (FluidModel *model, const unsigned int width, const unsigned int height, const Vector3r &pos, const Matrix3r &rotation, const Real velocity, const unsigned int type = 0)  

~Emitter()  

void emitParticles (std::vector<unsigned int> &reusedParticles, unsigned int &indexReuse, unsigned int &numEmittedParticles)  

void emitParticlesCircle (std::vector<unsigned int> &reusedParticles, unsigned int &indexReuse, unsigned int &numEmittedParticles)  

Real getNextEmitTime () const  

void setNextEmitTime (Real val)  

void setEmitStartTime (Real val)  

void setEmitEndTime (Real val)  

void step (std::vector<unsigned int> &reusedParticles, unsigned int &indexReuse, unsigned int &numEmittedParticles)  

void reset ()  

void saveState (BinaryFileWriter &binWriter)  

void loadState (Binary.FileReader &binReader)
```

Public Static Functions

```
Vector3r getSize (const Real width, const Real height, const int type)
```

Protected Functions

```
FORCE_INLINE bool inBox (const Vector3r &x, const Vector3r &xBox, const Matrix3r &rotBox)  

FORCE_INLINE bool inCylinder (const Vector3r &x, const Vector3r &xCyl, const Matrix3r &rotCyl)
```

Protected Attributes

```
FluidModel *m_model  
unsigned int m_width  
unsigned int m_height  
Vector3r m_x  
Matrix3r m_rotation  
Real m_velocity  
unsigned int m_type  
Real m_nextEmitTime  
Real m_emitStartTime  
Real m_emitEndTime  
unsigned int m_emitCounter
```

Class EmitterSystem

- Defined in file_SPlisHSPlasH_EmitterSystem.h

Class Documentation

```
class SPH::EmitterSystem
```

Public Functions

```
EmitterSystem(FluidModel *model)  
~EmitterSystem()  
void enableReuseParticles(const Vector3r &boxMin = Vector3r(-1, -1, -1), const Vector3r  
                           &boxMax = Vector3r(1, 1, 1))  
void disableReuseParticles()  
void addEmitter(const unsigned int width, const unsigned int height, const Vector3r &pos,  
                const Matrix3r &rotation, const Real velocity, const unsigned int type)  
unsigned int numEmitters() const  
std::vector<Emitter*> &getEmitters()  
unsigned int numReusedParticles() const  
unsigned int numEmittedParticles() const  
void step()  
void reset()  
void saveState(BinaryFileWriter &binWriter)  
void loadState(BinaryFileReader &binReader)
```

Protected Functions

```
void reuseParticles()
```

Protected Attributes

```
FluidModel *m_model
bool m_reuseParticles
Vector3r m_boxMin
Vector3r m_boxMax
unsigned int m_numberOfEmittedParticles
unsigned int m_numReusedParticles
std::vector<unsigned int> m_reusedParticles
std::vector<Emitter*> m_emitters
```

Protected Static Attributes

```
const unsigned int m_maxParticlesToReusePerStep = 50000
```

Class FluidModel

- Defined in file_SPlisHSPlasH_FluidModel.h

Inheritance Relationships

Base Type

- public ParameterObject

Class Documentation

```
class SPH::FluidModel : public ParameterObject
The fluid model stores the particle and simulation information.
```

Public Functions

```
FluidModel()
FluidModel(const FluidModel&) = delete
FluidModel &operator=(const FluidModel&) = delete
~FluidModel()
void init()
std::string getId() const
```

```
FORCE_INLINE Real getDensity0 () const
void setDensity0 (const Real v)
unsigned int getPointSetIndex () const
void addField (const FieldDescription &field)
const std::vector<FieldDescription> &getFields ()
const FieldDescription &getField (const unsigned int i)
const FieldDescription &getField (const std::string &name)
const unsigned int numberOfFields ()
void removeFieldByName (const std::string &fieldName)
void setNumActiveParticles (const unsigned int num)
unsigned int numberOfParticles () const
EmitterSystem *getEmitterSystem ()
void reset ()
void performNeighborhoodSearchSort ()
void initModel (const std::string &id, const unsigned int nFluidParticles, Vector3r *fluidParticles,
                Vector3r *fluidVelocities, const unsigned int nMaxEmitterParticles)
const unsigned int numParticles () const
unsigned int numActiveParticles () const
unsigned int getNumActiveParticles0 () const
void setNumActiveParticles0 (unsigned int val)
void emittedParticles (const unsigned int startIndex)
int getSurfaceTensionMethod () const
void setSurfaceTensionMethod (const int val)
int getViscosityMethod () const
void setViscosityMethod (const int val)
int getVorticityMethod () const
void setVorticityMethod (const int val)
int getDragMethod () const
void setDragMethod (const int val)
int getElasticityMethod () const
void setElasticityMethod (const int val)
SurfaceTensionBase *getSurfaceTensionBase ()
ViscosityBase *getViscosityBase ()
VorticityBase *getVorticityBase ()
DragBase *getDragBase ()
ElasticityBase *getElasticityBase ()
```

```

void setDragMethodChangedCallback (std::function<void>
    > const &callBackFct)

void setSurfaceMethodChangedCallback (std::function<void>
    > const &callBackFct)

void setViscosityMethodChangedCallback (std::function<void>
    > const &callBackFct)

void setVorticityMethodChangedCallback (std::function<void>
    > const &callBackFct)

void setElasticityMethodChangedCallback (std::function<void>
    > const &callBackFct)

void computeSurfaceTension ()

void computeViscosity ()

void computeVorticity ()

void computeDragForce ()

void computeElasticity ()

void saveState (BinaryFileWriter &binWriter)

void loadState (BinaryFileReader &binReader)

FORCE_INLINE Vector3r & getPosition0 (const unsigned int i)

FORCE_INLINE const Vector3r & getPosition0 (const unsigned int i) const

FORCE_INLINE void setPosition0 (const unsigned int i, const Vector3r &pos)

FORCE_INLINE Vector3r & getPosition (const unsigned int i)

FORCE_INLINE const Vector3r & getPosition (const unsigned int i) const

FORCE_INLINE void setPosition (const unsigned int i, const Vector3r &pos)

FORCE_INLINE Vector3r & getVelocity (const unsigned int i)

FORCE_INLINE const Vector3r & getVelocity (const unsigned int i) const

FORCE_INLINE void setVelocity (const unsigned int i, const Vector3r &vel)

FORCE_INLINE Vector3r & getVelocity0 (const unsigned int i)

FORCE_INLINE const Vector3r & getVelocity0 (const unsigned int i) const

FORCE_INLINE void setVelocity0 (const unsigned int i, const Vector3r &vel)

FORCE_INLINE Vector3r & getAcceleration (const unsigned int i)

FORCE_INLINE const Vector3r & getAcceleration (const unsigned int i) const

FORCE_INLINE void setAcceleration (const unsigned int i, const Vector3r &accel)

FORCE_INLINE const Real getMass (const unsigned int i) const

FORCE_INLINE Real & getMass (const unsigned int i)

FORCE_INLINE void setMass (const unsigned int i, const Real mass)

FORCE_INLINE const Real & getDensity (const unsigned int i) const

FORCE_INLINE Real & getDensity (const unsigned int i)

FORCE_INLINE void setDensity (const unsigned int i, const Real &val)

```

```
FORCE_INLINE unsigned int & getParticleId (const unsigned int i)
FORCE_INLINE const unsigned int & getParticleId (const unsigned int i) const
FORCE_INLINE const ParticleState & getParticleState (const unsigned int i) const
FORCE_INLINE ParticleState & getParticleState (const unsigned int i)
FORCE_INLINE void setParticleState (const unsigned int i, const ParticleState &val)
FORCE_INLINE const Real getVolume (const unsigned int i) const
FORCE_INLINE Real & getVolume (const unsigned int i)
```

Public Static Attributes

```
int NUM_PARTICLES = -1
int NUM_REUSE_PARTICLES = -1
int DENSITY0 = -1
int DRAG_METHOD = -1
int SURFACE_TENSION_METHOD = -1
int VISCOSITY_METHOD = -1
int VORTICITY_METHOD = -1
int ELASTICITY_METHOD = -1
int ENUM_DRAG_NONE = -1
int ENUM_DRAG_MACKLIN2014 = -1
int ENUM_DRAG_GISSLER2017 = -1
int ENUM_SURFACE TENSION_NONE = -1
int ENUM_SURFACE TENSION_BECKER2007 = -1
int ENUM_SURFACE TENSION_AKINCI2013 = -1
int ENUM_SURFACE TENSION_HE2014 = -1
int ENUM_VISCOSITY_NONE = -1
int ENUM_VISCOSITY_STANDARD = -1
int ENUM_VISCOSITY_XSPH = -1
int ENUM_VISCOSITY_BENDER2017 = -1
int ENUM_VISCOSITY_PEER2015 = -1
int ENUM_VISCOSITY_PEER2016 = -1
int ENUM_VISCOSITY_TAKAHASHI2015 = -1
int ENUM_VISCOSITY_WIELER2018 = -1
int ENUM_VORTICITY_NONE = -1
int ENUM_VORTICITY_MICROPOLAR = -1
int ENUM_VORTICITY_VC = -1
int ENUM_ELASTICITY_NONE = -1
```

```
int ENUM_ELASTICITY_BECKER2009 = -1
int ENUM_ELASTICITY_PEER2018 = -1
```

Protected Functions

```
void initParameters ()
void initMasses ()
void resizeFluidParticles (const unsigned int newSize)
    Resize the arrays containing the particle data.
void releaseFluidParticles ()
    Release the arrays containing the particle data.
```

Protected Attributes

```
std::string m_id
EmitterSystem *m_emitterSystem
std::vector<Real> m_masses
std::vector<Vector3r> m_a
std::vector<Vector3r> m_v0
std::vector<Vector3r> m_x0
std::vector<Vector3r> m_x
std::vector<Vector3r> m_v
std::vector<Real> m_density
std::vector<unsigned int> m_particleId
std::vector<ParticleState> m_particleState
Real m_V
SurfaceTensionMethods m_surfaceTensionMethod
SurfaceTensionBase *m_surfaceTension
ViscosityMethods m_viscosityMethod
ViscosityBase *m_viscosity
VorticityMethods m_vorticityMethod
VorticityBase *m_vorticity
DragMethods m_dragMethod
DragBase *m_drag
ElasticityMethods m_elasticityMethod
ElasticityBase *m_elasticity
std::vector<FieldDescription> m_fields
std::function<void ()> m_dragMethodChanged
```

```
std::function<void ()> m_surfaceTensionMethodChanged
std::function<void ()> m_viscosityMethodChanged
std::function<void ()> m_vorticityMethodChanged
std::function<void ()> m_elasticityMethodChanged
Real m_density0
unsigned int m_pointSetIndex
unsigned int m_numActiveParticles
unsigned int m_numActiveParticles0
```

Class GaussQuadrature

- Defined in file_SPlisHSPlasH_Utilsies_GaussQuadrature.h

Class Documentation

```
class SPH::GaussQuadrature
```

Public Types

```
using Integrand = std::function<double (Eigen::Vector3d const&)>
using Domain = Eigen::AlignedBox3d
```

Public Static Functions

```
double integrate (Integrand integrand, Domain const &domain, unsigned int p)
void exportSamples (unsigned int p)
```

Class JacobiPreconditioner1D

- Defined in file_SPlisHSPlasH_Utilsies_MatrixFreeSolver.h

Class Documentation

```
class SPH::JacobiPreconditioner1D
Matrix-free Jacobi preconditioner
```

Public Types

```
enum [anonymous]
    Values:
        enumerator ColsAtCompileTime = Eigen::Dynamic
        enumerator MaxColsAtCompileTime = Eigen::Dynamic
typedef SystemMatrixType::StorageIndex StorageIndex
typedef void (*DiagonalMatrixElementFct)(const unsigned int, Real&, void*)
```

Public Functions

```
JacobiPreconditioner1D()
void init(const unsigned int dim, DiagonalMatrixElementFct fct, void *userData)
Eigen::Index rows() const
Eigen::Index cols() const
Eigen::ComputationInfo info()
template<typename MatType>
JacobiPreconditioner1D &analyzePattern(const MatType&)

template<typename MatType>
JacobiPreconditioner1D &factorize(const MatType &mat)

template<typename MatType>
JacobiPreconditioner1D &compute(const MatType &mat)

template<typename Rhs, typename Dest>
void _solve_impl(const Rhs &b, Dest &x) const
template<typename Rhs>
const Eigen::Solve<JacobiPreconditioner1D, Rhs> solve(const Eigen::MatrixBase<Rhs> &b)
                                                const
```

Protected Attributes

```
unsigned int m_dim
DiagonalMatrixElementFct m_diagonalElementFct
    diagonal matrix element callback
void *mUserData
VectorXr m_invDiag
```

Class JacobiPreconditioner3D

- Defined in file_SPlisHSPlasH_Utilsies_MatrixFreeSolver.h

Class Documentation

```
class SPH::JacobiPreconditioner3D
Matrix-free Jacobi preconditioner
```

Public Types

```
enum [anonymous]
Values:
enumerator ColsAtCompileTime = Eigen::Dynamic
enumerator MaxColsAtCompileTime = Eigen::Dynamic
typedef SystemMatrixType::StorageIndex StorageIndex
typedef void (*DiagonalMatrixElementFct)(const unsigned int, Vector3r&, void*)
```

Public Functions

```
JacobiPreconditioner3D()

void init(const unsigned int dim, DiagonalMatrixElementFct fct, void *userData)
Eigen::Index rows() const
Eigen::Index cols() const
Eigen::ComputationInfo info()

template<typename MatType>
JacobiPreconditioner3D &analyzePattern(const MatType&)

template<typename MatType>
JacobiPreconditioner3D &factorize(const MatType &mat)

template<typename MatType>
JacobiPreconditioner3D &compute(const MatType &mat)

template<typename Rhs, typename Dest>
void _solve_impl(const Rhs &b, Dest &x) const

template<typename Rhs>
const Eigen::Solve<JacobiPreconditioner3D, Rhs> solve(const Eigen::MatrixBase<Rhs> &b)
const
```

Protected Attributes

```
unsigned int m_dim
DiagonalMatrixElementFct m_diagonalElementFct
    diagonal matrix element callback
void *m(userData
VectorXf m_invDiag
```

Class MathFunctions

- Defined in file_SPlisHSPlasH_Utils_MathFunctions.h

Class Documentation

```
class SPH::MathFunctions
```

Public Static Functions

```
void extractRotation (const Matrix3r &A, Quaternionr &q, const unsigned int maxIter)
    Implementation of the paper: Matthias Müller, Jan Bender, Nuttapong Chentanez and Miles Macklin, “A Robust Method to Extract the Rotational Part of Deformations”, ACM SIGGRAPH Motion in Games, 2016
void pseudoInverse (const Matrix3r &a, Matrix3r &res)
void svdWithInversionHandling (const Matrix3r &A, Vector3r &sigma, Matrix3r &U, Matrix3r &VT)
    Perform a singular value decomposition of matrix A: A = U * sigma * V^T. This function returns two proper rotation matrices U and V^T which do not contain a reflection. Reflections are corrected by the inversion handling proposed by Irving et al. 2004.
void eigenDecomposition (const Matrix3r &A, Matrix3r &eigenVecs, Vector3r &eigenVals)
void jacobiRotate (Matrix3r &A, Matrix3r &R, int p, int q)
void getOrthogonalVectors (const Vector3r &vec, Vector3r &x, Vector3r &y)
    Returns two orthogonal vectors to vec which are also orthogonal to each other.
```

Class MatrixReplacement

- Defined in file_SPlisHSPlasH_Utils_MatrixFreeSolver.h

Inheritance Relationships

Base Type

- public Eigen::EigenBase< MatrixReplacement >

Class Documentation

```
class SPH::MatrixReplacement : public Eigen::EigenBase<MatrixReplacement>
    Replacement of the matrix in the linear system which is required for a matrix-free solver.
```

Public Types

```
enum [anonymous]
    Values:
        enumerator ColsAtCompileTime = Eigen::Dynamic
        enumerator MaxColsAtCompileTime = Eigen::Dynamic
        enumerator IsRowMajor = false
    typedef Real Scalar
    typedef Real RealScalar
    typedef int StorageIndex
    typedef void (*MatrixVecProdFct)(const Real*, Real*, void*)
```

Public Functions

```
Index rows() const
Index cols() const
template<typename Rhs>
Eigen::Product<MatrixReplacement, Rhs, Eigen::AliasFreeProduct> operator* (const
    Eigen::MatrixBase<Rhs>
    &x) const
MatrixReplacement (const unsigned int dim, MatrixVecProdFct fct, void *userData)
void *getUserData()
MatrixVecProdFct getMatrixVecProdFct()
```

Protected Attributes

```
unsigned int m_dim
void *m(userData
MatrixVecProdFct m_matrixVecProdFct
matrix vector product callback
```

Class MicropolarModel_Bender2017

- Defined in file_SPlisHSPlasH_Vorticity_MicropolarModel_Bender2017.h

Inheritance Relationships

Base Type

- public SPH::VorticityBase (*Class VorticityBase*)

Class Documentation

```
class SPH::MicropolarModel_Bender2017 : public SPH::VorticityBase
```

This class implements the micropolar material model introduced by Bender et al. [9].

Public Functions

```
MicropolarModel_Bender2017 (FluidModel *model)
~MicropolarModel_Bender2017 (void)
void step ()
void reset ()
void performNeighborhoodSearchSort ()
FORCE_INLINE const Vector3r & getAngularAcceleration (const unsigned int i) const
FORCE_INLINE Vector3r & getAngularAcceleration (const unsigned int i)
FORCE_INLINE void setAngularAcceleration (const unsigned int i, const Vector3r &val)
FORCE_INLINE const Vector3r & getAngularVelocity (const unsigned int i) const
FORCE_INLINE Vector3r & getAngularVelocity (const unsigned int i)
FORCE_INLINE void setAngularVelocity (const unsigned int i, const Vector3r &val)
```

Public Static Attributes

```
int VISCOSITY_OMEGA = -1  
int INERTIA_INVERSE = -1
```

Protected Functions

```
void initParameters()
```

Protected Attributes

```
std::vector<Vector3r> m-angularAcceleration  
std::vector<Vector3r> m_omega  
Real m_viscosityOmega  
Real m_inertiaInverse
```

Class NonPressureForceBase

- Defined in file_SPlisHSPlasH_NonPressureForceBase.h

Inheritance Relationships

Base Type

- public ParameterObject

Derived Types

- public SPH::DragBase (*Class DragBase*)
- public SPH::ElasticityBase (*Class ElasticityBase*)
- public SPH::SurfaceTensionBase (*Class SurfaceTensionBase*)
- public SPH::ViscosityBase (*Class ViscosityBase*)
- public SPH::VorticityBase (*Class VorticityBase*)

Class Documentation

```
class SPH::NonPressureForceBase : public ParameterObject  
Base class for all non-pressure force methods.  
Subclassed by SPH::DragBase, SPH::ElasticityBase, SPH::SurfaceTensionBase, SPH::ViscosityBase,  
SPH::VorticityBase
```

Public Functions

```
NonPressureForceBase (FluidModel *model)
NonPressureForceBase (const NonPressureForceBase&) = delete
NonPressureForceBase &operator= (const NonPressureForceBase&) = delete
~NonPressureForceBase (void)
void step () = 0
void reset ()
void performNeighborhoodSearchSort ()
void emittedParticles (const unsigned int startIndex)
void saveState (BinaryFileWriter &binWriter)
void loadState (Binary.FileReader &binReader)
FluidModel *getModel ()
void init ()
```

Protected Attributes

FluidModel ***m_model**

Class PoissonDiskSampling

- Defined in file_SPlisHSPlasH_Utilsities_PoissonDiskSampling.h

Nested Relationships

Nested Types

- Struct PoissonDiskSampling::CellPosHasher*
- Struct PoissonDiskSampling::HashEntry*
- Struct PoissonDiskSampling::InitialPointInfo*

Class Documentation

class SPH::PoissonDiskSampling

This class implements a Poisson disk sampling for the surface of 3D models.

Public Functions

PoissonDiskSampling()

```
void sampleMesh (const unsigned int numVertices, const Vector3r *vertices, const unsigned int numFaces, const unsigned int *faces, const Real minRadius, const unsigned int numTrials, unsigned int distanceNorm, std::vector<Vector3r> &samples)
```

Performs the poisson sampling with the respective parameters. Compare http://graphics.cs.umass.edu/pubs/sa_2010.pdf

Parameters

- mesh: mesh data of sampled body
- vertices: vertex data of sampled data
- sampledVertices: sampled vertices that will be returned
- minRadius: minimal distance of sampled vertices
- numTestpointsPerFace: # of generated test points per face of body
- distanceNorm: 0: euclidean norm, 1: approx geodesic distance
- numTrials: # of iterations used to find samples

Public Static Functions

FORCE_INLINE int floor (const Real v)

struct HashEntry

Struct to store the hash entry (spatial hashing)

Public Functions

HashEntry()

Public Members

std::vector<unsigned int> **samples**

unsigned int **startIndex**

struct InitialPointInfo

Struct to store the information of the initial points.

Public Members

CellPos **cP**

Vector3r **pos**

unsigned int **ID**

Class Poly6Kernel

- Defined in file_SPlisHSPlasH_SPHKernels.h

Class Documentation

```
class SPH::Poly6Kernel
Poly6 kernel.
```

Public Static Functions

```
Real getRadius ()
void setRadius (Real val)

Real W (const Real r)
W(r,h) = (315/(64 pi h^9))(h^2-|r|^2)^3 = (315/(64 pi h^9))(h^2-r*r)^3

Real W (const Vector3r &r)
Vector3r gradW (const Vector3r &r)
grad(W(r,h)) = r(-945/(32 pi h^9))(h^2-|r|^2)^2 = r(-945/(32 pi h^9))(h^2-r*r)^2

Real laplacianW (const Vector3r &r)
laplacian(W(r,h)) = (-945/(32 pi h^9))(h^2-|r|^2)(-7|r|^2+3h^2) = (-945/(32 pi h^9))(h^2-r*r)(3 h^2-7 r*r)

Real W_zero ()
```

Protected Static Attributes

```
Real m_radius
Real m_k
Real m_l
Real m_m
Real m_W_zero
```

Template Class PrecomputedKernel

- Defined in file_SPlisHSPlasH_SPHKernels.h

Class Documentation

```
template<typename KernelType, unsigned int resolution = 10000u>
class SPH::PrecomputedKernel
Precomputed kernel which is based on a lookup table as described by Bender and Koschier [5], [6].
The lookup tables can be used in combination with any kernel.
```

Public Static Functions

```
Real getRadius ()  
void setRadius (Real val)  
Real W (const Vector3r &r)  
Real W (const Real r)  
Vector3r gradW (const Vector3r &r)  
Real W_zero ()
```

Protected Static Attributes

```
Real m_W[resolution]  
Real m_gradW[resolution + 1]  
Real m_radius  
Real m_radius2  
Real m_invStepSize  
Real m_W_zero
```

Class RegularSampling2D

- Defined in file_SPlisHSPlasH_UtilsRegularSampling2D.h

Class Documentation

```
class SPH::RegularSampling2D
```

This class implements a per-triangle regular sampling for the surface of 3D models.

Public Functions

```
RegularSampling2D ()
```

Public Static Functions

```
void sampleMesh (const Matrix3r &rotation, const Vector3r &translation, const unsigned numVertices, const Vector3r *vertices, const unsigned int numFaces, const unsigned int *faces, const Real maxDistance, std::vector<Vector3r> &samples)  
Performs the poisson sampling with the respective parameters. Compare http://graphics.cs.umass.edu/pubs/sa\_2010.pdf
```

Parameters

- rotation: rotation of the mesh
- translation: translation of the mesh
- numVertices: number of mesh vertices

- `vertices`: vertex data of sampled data
- `numFaces`: number of faces in the mesh
- `faces`: face data of sampled mesh
- `maxDistance`: maximal distance of sampled vertices
- `samples`: vector to store the samples

Class RegularTriangleSampling

- Defined in file_SPlisHSPlasH_Utils_RandomSampling.h

Class Documentation

`class SPH::RegularTriangleSampling`

This class implements a per-triangle regular sampling for the surface of 3D models.

Public Functions

`RegularTriangleSampling()`

Public Static Functions

```
void sampleMesh(const unsigned int numVertices, const Vector3r *vertices, const unsigned int numFaces, const unsigned int *faces, const Real maxDistance, std::vector<Vector3r> &samples)
```

Performs the poisson sampling with the respective parameters. Compare http://graphics.cs.umass.edu/pubs/sa_2010.pdf

Parameters

- `numVertices`: number of mesh vertices
- `vertices`: vertex data of sampled data
- `numFaces`: number of faces in the mesh
- `faces`: face data of sampled mesh
- `maxDistance`: maximal distance of sampled vertices
- `samples`: vector to store the samples

Class RigidBodyObject

- Defined in file_SPlisHSPlasH_RigidBodyObject.h

Inheritance Relationships

Derived Type

- public SPH::StaticRigidBody (*Class StaticRigidBody*)

Class Documentation

class SPH::RigidBodyObject

Base class for rigid body objects.

Subclassed by *SPH::StaticRigidBody*

Public Functions

```
~RigidBodyObject ()  
bool isDynamic () const = 0  
Real const getMass () const = 0  
Vector3r const &getPosition () const = 0  
void setPosition (const Vector3r &x) = 0  
Vector3r getWorldSpacePosition () const = 0  
Vector3r const &getVelocity () const = 0  
void setVelocity (const Vector3r &v) = 0  
Matrix3r const &getRotation () const = 0  
void setRotation (const Matrix3r &r) = 0  
Matrix3r getWorldSpaceRotation () const = 0  
Vector3r const &getAngularVelocity () const = 0  
void setAngularVelocity (const Vector3r &v) = 0  
void addForce (const Vector3r &f) = 0  
void addTorque (const Vector3r &t) = 0  
const std::vector<Vector3r> &getVertices () const = 0  
const std::vector<Vector3r> &getVertexNormals () const = 0  
const std::vector<unsigned int> &getFaces () const = 0
```

Class SimpleQuadrature

- Defined in file_SPlisHSPlasH_Utilsies_SimpleQuadrature.h

Class Documentation

```
class SPH::SimpleQuadrature
```

Public Types

```
using Integrand = std::function<double (Eigen::Vector3d const&) >
using Domain = Eigen::AlignedBox3d
```

Public Static Functions

```
void determineSamplePointsInSphere (const double radius, unsigned int p)
void determineSamplePointsInCircle (const double radius, unsigned int p)
double integrate (Integrand integrand)
```

Public Static Attributes

```
std::vector<Eigen::Vector3d> m_samplePoints
double m_volume = 0.0
```

Class Simulation

- Defined in file_SPlisHSPlasH_Simulation.h

Inheritance Relationships

Base Type

- public ParameterObject

Class Documentation

```
class SPH::Simulation : public ParameterObject
```

Class to manage the current simulation time and the time step size. This class is a singleton.

Public Types

```
typedef PrecomputedKernel<CubicKernel, 10000> PrecomputedCubicKernel
```

Public Functions

```
Simulation()
Simulation(const Simulation&) = delete
Simulation &operator=(const Simulation&) = delete
~Simulation()

void init(const Real particleRadius, const bool sim2D)
void reset()

void addFluidModel(const std::string &id, const unsigned int nFluidParticles, Vector3r *fluidParticles, Vector3r *fluidVelocities, const unsigned int nMaxEmitterParticles)
FluidModel *getFluidModel(const unsigned int index)
FluidModel *getFluidModelFromPointSet(const unsigned int pointSetIndex)
const unsigned int numberOfFluidModels() const
void addBoundaryModel(BoundaryModel *bm)
BoundaryModel *getBoundaryModel(const unsigned int index)
BoundaryModel *getBoundaryModelFromPointSet(const unsigned int pointSetIndex)
const unsigned int numberOfBoundaryModels() const
void updateBoundaryVolume()

AnimationFieldSystem *getAnimationFieldSystem()
BoundaryHandlingMethods getBoundaryHandlingMethod() const
void setBoundaryHandlingMethod(BoundaryHandlingMethods val)

int getKernel() const
void setKernel(int val)

int getGradKernel() const
void setGradKernel(int val)

FORCE_INLINE Real W_zero() const
FORCE_INLINE Real W(const Vector3r &r) const
FORCE_INLINE Vector3r gradW(const Vector3r &r)

int getSimulationMethod() const
void setSimulationMethod(const int val)

void setSimulationMethodChangedCallback(std::function<void>
    > const &callBackFct

TimeStep *getTimeStep()

bool is2DSimulation()
```

```

bool zSortEnabled()
void setParticleRadius (Real val)
Real getParticleRadius () const
Real getSupportRadius () const
void updateTimeStepSize ()
    Update time step size depending on the chosen method.
void updateTimeStepSizeCFL ()
    Update time step size by CFL condition.
void performNeighborhoodSearch ()
    Perform the neighborhood search for all fluid particles.
void performNeighborhoodSearchSort ()
void computeNonPressureForces ()
void animateParticles ()
void emitParticles ()
void emittedParticles (FluidModel *model, const unsigned int startIndex)
NeighborhoodSearch *getNeighborhoodSearch ()
void saveState (BinaryFileWriter &binWriter)
void loadState (Binary.FileReader &binReader)
FORCE_INLINE unsigned int numberOfPointSets () const
FORCE_INLINE unsigned int numberOfNeighbors (const unsigned int pointSetIndex, const ...)
FORCE_INLINE unsigned int getNeighbor (const unsigned int pointSetIndex, const unsigned int neighborIndex)
FORCE_INLINE const unsigned int * getNeighborList (const unsigned int pointSetIndex, const unsigned int neighborCount)

```

Public Static Functions

```

Simulation *getCurrent ()
void setCurrent (Simulation *tm)
bool hasCurrent ()

```

Public Static Attributes

```

int SIM_2D = -1
int PARTICLE_RADIUS = -1
int GRAVITATION = -1
int CFL_METHOD = -1
int CFL_FACTOR = -1
int CFL_MIN_TIMESTEP_SIZE = -1
int CFL_MAX_TIMESTEP_SIZE = -1
int ENABLE_Z_SORT = -1

```

```
int KERNEL_METHOD = -1
int GRAD_KERNEL_METHOD = -1
int ENUM_KERNEL_CUBIC = -1
int ENUM_KERNEL_WENDLANDQUINTICC2 = -1
int ENUM_KERNEL_POLY6 = -1
int ENUM_KERNEL_SPIKY = -1
int ENUM_KERNEL_PRECOMPUTED_CUBIC = -1
int ENUM_KERNEL_CUBIC_2D = -1
int ENUM_KERNEL_WENDLANDQUINTICC2_2D = -1
int ENUM_GRADKERNEL_CUBIC = -1
int ENUM_GRADKERNEL_WENDLANDQUINTICC2 = -1
int ENUM_GRADKERNEL_POLY6 = -1
int ENUM_GRADKERNEL_SPIKY = -1
int ENUM_GRADKERNEL_PRECOMPUTED_CUBIC = -1
int ENUM_GRADKERNEL_CUBIC_2D = -1
int ENUM_GRADKERNEL_WENDLANDQUINTICC2_2D = -1
int SIMULATION_METHOD = -1
int ENUM_CFL_NONE = -1
int ENUM_CFL_STANDARD = -1
int ENUM_CFL_ITER = -1
int ENUM_SIMULATION_WCSPH = -1
int ENUM_SIMULATION_PCISPH = -1
int ENUM_SIMULATION_PBF = -1
int ENUM_SIMULATION_IISPH = -1
int ENUM_SIMULATION_DFSPH = -1
int ENUM_SIMULATION_PF = -1
int BOUNDARY_HANDLING_METHOD = -1
int ENUM_AKINCI2012 = -1
int ENUM_KOSCHIER2017 = -1
int ENUM_BENDER2019 = -1
```

Protected Functions

```
void initParameters()
```

Protected Attributes

```
std::vector<FluidModel*> m_fluidModels
std::vector<BoundaryModel*> m_boundaryModels
NeighborhoodSearch *m_neighborhoodSearch
AnimationFieldSystem *m_animationFieldSystem
int m_cflMethod
Real m_cflFactor
Real m_cflMinTimeStepSize
Real m_cflMaxTimeStepSize
int m_kernelMethod
int m_gradKernelMethod
Real m_W_zero
Real (*m_kernelFct)(const Vector3r&)
Vector3r (*m_gradKernelFct)(const Vector3r &r)
SimulationMethods m_simulationMethod
TimeStep *m_timeStep
Vector3r m_gravitation
Real m_particleRadius
Real m_supportRadius
bool m_sim2D
bool m_enableZSort
std::function<void ()> m_simulationMethodChanged
int m_boundaryHandlingMethod
```

Class **SimulationDataDFSPH**

- Defined in file _SPlisHSPlasH_DFSRH_SimulationDataDFSPH.h

Class Documentation

```
class SPH::SimulationDataDFSPH
```

Simulation data which is required by the method Divergence-free Smoothed Particle Hydrodynamics introduced by Bender and Koschier [5], [6].

Public Functions

SimulationDataDFSPH ()

```
~SimulationDataDFSPH()
```

```
void init()
```

Initialize the arrays containing the particle data.

```
void cleanup()
```

Release the arrays containing the particle data.

```
void reset()
```

Reset the particle data.

```
void performNeighborhoodSearchSort ()
```

Important: First call `m_model->performNeighborhoodSearchSort()` to call the `z_sort` of the neighborhood search.

```
void emittedParticles (FluidModel *model, const unsigned int startIndex)
```

```
FORCE_INLINE const Real getFactor (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE Real & getFactor (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE void setFactor (const unsigned int fluidIndex, const unsigned int i, const
FORCE_INLINE const Real getKappa (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE Real & getKappa (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE void setKappa (const unsigned int fluidIndex, const unsigned int i, const
FORCE_INLINE const Real getKappaV (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE Real & getKappaV (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE void setKappaV (const unsigned int fluidIndex, const unsigned int i, const
FORCE_INLINE const Real getDensityAdv (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE Real & getDensityAdv (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE void setDensityAdv (const unsigned int fluidIndex, const unsigned int i,
```

Protected Attributes

```
std::vector<std::vector<Real>> m_factor
```

factor α_i [5]

```
std::vector<std::vector<Real>> m_kappa
```

stores κ value of last time step for a warm start of the pressure solver

```
std::vector<std::vector<Real>> m_kappaV
```

stores κ^v value of last time step for a warm start of the divergence solver

```
std::vector<std::vector<Real>> m_density_adv
    advected density
```

Class SimulationDataIISPH

- Defined in file_SPlisHSPlasH_IISPH_SimulationDataIISPH.h

Class Documentation

class SPH::SimulationDataIISPH

Simulation data which is required by the method Implicit Incompressible SPH introduced by Ihmsen et al. [13].

Public Functions

SimulationDataIISPH()

~SimulationDataIISPH()

void init()

Initialize the arrays containing the particle data.

void cleanup()

Release the arrays containing the particle data.

void reset()

Reset the particle data.

void performNeighborhoodSearchSort()

Important: First call m_model->*performNeighborhoodSearchSort()* to call the z_sort of the neighborhood search.

void emittedParticles (FluidModel *model, const unsigned int startIndex)

FORCE_INLINE const Real getAii (const unsigned int fluidIndex, const unsigned int i) const;

FORCE_INLINE Real & getAii (const unsigned int fluidIndex, const unsigned int i);

FORCE_INLINE void setAii (const unsigned int fluidIndex, const unsigned int i, const Real value);

FORCE_INLINE Vector3r & getDii (const unsigned int fluidIndex, const unsigned int i);

FORCE_INLINE const Vector3r & getDii (const unsigned int fluidIndex, const unsigned int i) const;

FORCE_INLINE void setDii (const unsigned int fluidIndex, const unsigned int i, const Vector3r & value);

FORCE_INLINE Vector3r & getDij_pj (const unsigned int fluidIndex, const unsigned int i);

FORCE_INLINE const Vector3r & getDij_pj (const unsigned int fluidIndex, const unsigned int i) const;

FORCE_INLINE void setDij_pj (const unsigned int fluidIndex, const unsigned int i, const Vector3r & value);

FORCE_INLINE const Real getDensityAdv (const unsigned int fluidIndex, const unsigned int i) const;

FORCE_INLINE Real & getDensityAdv (const unsigned int fluidIndex, const unsigned int i);

FORCE_INLINE void setDensityAdv (const unsigned int fluidIndex, const unsigned int i, const Real value);

FORCE_INLINE const Real getPressure (const unsigned int fluidIndex, const unsigned int i) const;

FORCE_INLINE Real & getPressure (const unsigned int fluidIndex, const unsigned int i);

FORCE_INLINE void setPressure (const unsigned int fluidIndex, const unsigned int i, const Real value);

```
FORCE_INLINE const Real getLastPressure (const unsigned int fluidIndex, const unsigned
FORCE_INLINE Real & getLastPressure (const unsigned int fluidIndex, const unsigned int
FORCE_INLINE void setLastPressure (const unsigned int fluidIndex, const unsigned int i
FORCE_INLINE Vector3r & getPressureAccel (const unsigned int fluidIndex, const unsigned
FORCE_INLINE const Vector3r & getPressureAccel (const unsigned int fluidIndex, const un
FORCE_INLINE void setPressureAccel (const unsigned int fluidIndex, const unsigned int i
```

Protected Attributes

```
std::vector<std::vector<Real>> m_aai
std::vector<std::vector<Vector3r>> m_dii
std::vector<std::vector<Vector3r>> m_dij_pj
std::vector<std::vector<Real>> m_density_adv
std::vector<std::vector<Real>> m_pressure
std::vector<std::vector<Real>> m_lastPressure
std::vector<std::vector<Vector3r>> m_pressureAccel
```

Class SimulationDataPBF

- Defined in file_SPlisHSPlasH_PBF_SimulationDataPBF.h

Class Documentation

```
class SPH::SimulationDataPBF
```

Simulation data which is required by the method Position-Based Fluids introduced by Macklin and Mueller [17], [7], [8].

Public Functions

```
SimulationDataPBF()
```

```
~SimulationDataPBF()
```

```
void init()
```

Initialize the arrays containing the particle data.

```
void cleanup()
```

Release the arrays containing the particle data.

```
void reset()
```

Reset the particle data.

```
void performNeighborhoodSearchSort()
```

Important: First call m_model->*performNeighborhoodSearchSort()* to call the z_sort of the neighborhood search.

```
void emittedParticles (FluidModel *model, const unsigned int startIndex)
```

```
FORCE_INLINE const Real & getLambda (const unsigned int fluidIndex, const unsigned int
```

```

FORCE_INLINE Real & getLambda (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE void setLambda (const unsigned int fluidIndex, const unsigned int i, const
FORCE_INLINE Vector3r & getDeltaX (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE const Vector3r & getDeltaX (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE void setDeltaX (const unsigned int fluidIndex, const unsigned int i, const
FORCE_INLINE Vector3r & getLastPosition (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE const Vector3r & getLastPosition (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE void setLastPosition (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE Vector3r & getOldPosition (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE const Vector3r & getOldPosition (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE void setOldPosition (const unsigned int fluidIndex, const unsigned int i,

```

Protected Attributes

```

std::vector<std::vector<Real>> m_lambda
std::vector<std::vector<Vector3r>> m_deltaX
std::vector<std::vector<Vector3r>> m_oldX
std::vector<std::vector<Vector3r>> m_lastX

```

Class SimulationDataPCISPH

- Defined in file_SPlisHSPlasH_PCISPH_SimulationDataPCISPH.h

Class Documentation

```
class SPH::SimulationDataPCISPH
```

Simulation data which is required by the method Predictive-corrective Incompressible SPH introduced by Soenthaler and Pajarola [23].

Public Functions

```

SimulationDataPCISPH()
~SimulationDataPCISPH()

void init()
    Initialize the arrays containing the particle data.

void cleanup()
    Release the arrays containing the particle data.

void reset()
    Reset the particle data.

void performNeighborhoodSearchSort()
    Important: First call m_model->performNeighborhoodSearchSort() to call the z_sort of the neighborhood search.

```

```
Real getPCISPH_ScalingFactor (const unsigned int fluidIndex)
void emittedParticles (FluidModel *model, const unsigned int startIndex)
FORCE_INLINE Vector3r & getLastPosition (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE const Vector3r & getLastPosition (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE void setLastPosition (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE Vector3r & getLastVelocity (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE const Vector3r & getLastVelocity (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE void setLastVelocity (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE const Real getDensityAdv (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE Real & getDensityAdv (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE void setDensityAdv (const unsigned int fluidIndex, const unsigned int i, const Real value)
FORCE_INLINE const Real getPressure (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE Real & getPressure (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE void setPressure (const unsigned int fluidIndex, const unsigned int i, const Real value)
FORCE_INLINE Vector3r & getPressureAccel (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE const Vector3r & getPressureAccel (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE void setPressureAccel (const unsigned int fluidIndex, const unsigned int i, const Vector3r & value)
```

Protected Attributes

```
std::vector<Real> m_pcisph_factor
std::vector<std::vector<Vector3r>> m_lastX
std::vector<std::vector<Vector3r>> m_lastV
std::vector<std::vector<Real>> m_densityAdv
std::vector<std::vector<Real>> m_pressure
std::vector<std::vector<Vector3r>> m_pressureAccel
```

Class SimulationDataPF

- Defined in file_SPlisHSPlasH_PF_SimulationDataPF.h

Class Documentation

```
class SPH::SimulationDataPF
Simulation data which is required by the method Projective Fluids introduced by Weiler, Koschier and Bender [25].
```

Public Functions

```

SimulationDataPF()
~SimulationDataPF()

void init()
    Initialize the arrays containing the particle data.

void cleanup()
    Release the arrays containing the particle data.

void reset()
    Reset the particle data.

void performNeighborhoodSearchSort()
    Important: First call m_model->performNeighborhoodSearchSort() to call the z_sort of the neighborhood search.

void emittedParticles (FluidModel *model, const unsigned int startIndex)
FORCE_INLINE const Vector3r getOldPosition (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE Vector3r & getOldPosition (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE void setOldPosition (const unsigned int fluidIndex, const unsigned int i, const Vector3r & value)
FORCE_INLINE const unsigned int getNumFluidNeighbors (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE unsigned int & getNumFluidNeighbors (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE void setNumFluidNeighbors (const unsigned int fluidIndex, const unsigned int i, const unsigned int value)
FORCE_INLINE const Vector3r & getS (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE Vector3r & gets (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE void sets (const unsigned int fluidIndex, const unsigned int i, const Vector3r & value)
FORCE_INLINE const Vector3r & getDiag (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE Vector3r & getDiag (const unsigned int fluidIndex, const unsigned int i)
FORCE_INLINE void setDiag (const unsigned int fluidIndex, const unsigned int i, const Vector3r & value)
FORCE_INLINE const unsigned int & getParticleOffset (const unsigned int fluidIndex) const

```

Protected Attributes

```

std::vector<std::vector<Vector3r>> m_old_position
    particle position from last timestep

std::vector<std::vector<unsigned int>> m_num_fluid_neighbors
    number of neighbors that are fluid particles

std::vector<std::vector<Vector3r>> m_s
    positions predicted from momentum

std::vector<std::vector<Vector3r>> m_mat_diag
    diagonal of system matrix, used by preconditioner

std::vector<unsigned int> m_particleOffset

```

Class SimulationDataWCSPH

- Defined in file_SPlisHSPlasH_WCSPH_SimulationDataWCSPH.h

Class Documentation

```
class SPH::SimulationDataWCSPH
```

Simulation data which is required by the method Weakly Compressible SPH for Free Surface Flows introduced by Becker and Teschner [3].

Public Functions

```
SimulationDataWCSPH()
```

```
~SimulationDataWCSPH()
```

```
void init()
```

Initialize the arrays containing the particle data.

```
void cleanup()
```

Release the arrays containing the particle data.

```
void reset()
```

Reset the particle data.

```
void performNeighborhoodSearchSort()
```

Important: First call m_model->*performNeighborhoodSearchSort()* to call the z_sort of the neighborhood search.

```
void emittedParticles (FluidModel *model, const unsigned int startIndex)
```

```
FORCE_INLINE const Real getPressure (const unsigned int fluidIndex, const unsigned int
```

```
FORCE_INLINE Real & getPressure (const unsigned int fluidIndex, const unsigned int i)
```

```
FORCE_INLINE void setPressure (const unsigned int fluidIndex, const unsigned int i, const
```

```
FORCE_INLINE Vector3r & getPressureAccel (const unsigned int fluidIndex, const unsigned int
```

```
FORCE_INLINE const Vector3r & getPressureAccel (const unsigned int fluidIndex, const unsigned int
```

```
FORCE_INLINE void setPressureAccel (const unsigned int fluidIndex, const unsigned int
```

Protected Attributes

```
std::vector<std::vector<Real>> m_pressure
```

```
std::vector<std::vector<Vector3r>> m_pressureAccel
```

Class SpikyKernel

- Defined in file_SPlisHSPlasH_SPHKernels.h

Class Documentation

```
class SPH::SpikyKernel
    Spiky kernel.
```

Public Static Functions

```
Real getRadius ()
void setRadius (Real val)

Real W (const Real r)
     $W(r,h) = 15/(\pi \cdot h^6) \cdot (h-r)^3$ 

Real W (const Vector3r &r)

Vector3r gradW (const Vector3r &r)
     $\text{grad}(W(r,h)) = -r(45/(\pi \cdot h^6) \cdot (h-r)^2)$ 

Real W_zero ()
```

Protected Static Attributes

```
Real m_radius
Real m_k
Real m_l
Real m_W_zero
```

Class StaticRigidBody

- Defined in file_SPlisHSPlasH_StaticRigidBody.h

Inheritance Relationships

Base Type

- public SPH::RigidBodyObject (*Class RigidBodyObject*)

Class Documentation

```
class SPH::StaticRigidBody : public SPH::RigidBodyObject
```

This class stores the information of a static rigid body which is not part of a rigid body simulation.

Public Functions

```
StaticRigidBody()
bool isDynamic() const
Real const getMass() const
Vector3r const &getPosition() const
void setPosition(const Vector3r &x)
Vector3r getWorldSpacePosition() const
Vector3r const &getVelocity() const
void setVelocity(const Vector3r &v)
Matrix3r const &getRotation() const
void setRotation(const Matrix3r &r)
Matrix3r getWorldSpaceRotation() const
Vector3r const &getAngularVelocity() const
void setAngularVelocity(const Vector3r &v)
void addForce(const Vector3r &f)
void addTorque(const Vector3r &t)
const std::vector<Vector3r> &getVertices() const
const std::vector<Vector3r> &getVertexNormals() const
const std::vector<unsigned int> &getFaces() const
void setWorldSpacePosition(const Vector3r &x)
void setWorldSpaceRotation(const Matrix3r &r)
TriangleMesh &getGeometry()
```

Protected Attributes

```
Vector3r m_x
Vector3r m_x_world
Vector3r m_zero
Matrix3r m_R
Matrix3r m_R_world
TriangleMesh m_geometry
```

Class SurfaceTension_Akinci2013

- Defined in file_SPlisHSPlasH_SurfaceTension_SurfaceTension_Akinci2013.h

Inheritance Relationships

Base Type

- public SPH::SurfaceTensionBase (*Class SurfaceTensionBase*)

Class Documentation

```
class SPH::SurfaceTension_Akinci2013 : public SPH::SurfaceTensionBase
```

This class implements the surface tension method introduced by Akinci et al. [2].

Public Functions

```
SurfaceTension_Akinci2013 (FluidModel *model)
~SurfaceTension_Akinci2013 (void)
void step ()
void reset ()
void computeNormals ()
void performNeighborhoodSearchSort ()
FORCE_INLINE Vector3r & getNormal (const unsigned int i)
FORCE_INLINE const Vector3r & getNormal (const unsigned int i) const
FORCE_INLINE void setNormal (const unsigned int i, const Vector3r &val)
```

Protected Attributes

```
std::vector<Vector3r> m_normals
```

Class SurfaceTension_Becker2007

- Defined in file_SPlisHSPlasH_SurfaceTension_SurfaceTension_Becker2007.h

Inheritance Relationships

Base Type

- public SPH::SurfaceTensionBase (*Class SurfaceTensionBase*)

Class Documentation

```
class SPH::SurfaceTension_Becker2007 : public SPH::SurfaceTensionBase
```

This class implements the surface tension method introduced by Becker and Teschner [3].

Public Functions

```
SurfaceTension_Becker2007(FluidModel *model)  
~SurfaceTension_Becker2007(void)  
void step()  
void reset()
```

Class SurfaceTension_He2014

- Defined in file_SPlisHSPlasH_SurfaceTension_SurfaceTension_He2014.h

Inheritance Relationships

Base Type

- public SPH::SurfaceTensionBase (*Class SurfaceTensionBase*)

Class Documentation

```
class SPH::SurfaceTension_He2014 : public SPH::SurfaceTensionBase
```

This class implements the surface tension method introduced by He et al. [12].

Public Functions

```
SurfaceTension_He2014(FluidModel *model)  
~SurfaceTension_He2014(void)  
void step()  
void reset()  
void performNeighborhoodSearchSort()  
FORCE_INLINE const Real getColor(const unsigned int i) const  
FORCE_INLINE Real & getColor(const unsigned int i)  
FORCE_INLINE void setColor(const unsigned int i, const Real p)  
FORCE_INLINE const Real getGradC2(const unsigned int i) const  
FORCE_INLINE Real & getGradC2(const unsigned int i)  
FORCE_INLINE void setGradC2(const unsigned int i, const Real p)
```

Protected Attributes

```
std::vector<Real> m_color
std::vector<Real> m_gradC2
```

Class SurfaceTensionBase

- Defined in file_SPlisHSPlasH_SurfaceTension_SurfaceTensionBase.h

Inheritance Relationships

Base Type

- public SPH::NonPressureForceBase (*Class NonPressureForceBase*)

Derived Types

- public SPH::SurfaceTension_Akinci2013 (*Class SurfaceTension_Akinci2013*)
- public SPH::SurfaceTension_Becker2007 (*Class SurfaceTension_Becker2007*)
- public SPH::SurfaceTension_He2014 (*Class SurfaceTension_He2014*)

Class Documentation

```
class SPH::SurfaceTensionBase : public SPH::NonPressureForceBase
```

Base class for all surface tension methods.

Subclassed by *SPH::SurfaceTension_Akinci2013*, *SPH::SurfaceTension_Becker2007*,
SPH::SurfaceTension_He2014

Public Functions

```
SurfaceTensionBase (FluidModel *model)
~SurfaceTensionBase (void)
```

Public Static Attributes

```
int SURFACE_TENSION = -1
int SURFACE_TENSION_BOUNDARY = -1
```

Protected Functions

```
void initParameters()
```

Protected Attributes

Real m_surfaceTension

Real m_surfaceTensionBoundary

Class TimeIntegration

- Defined in file_SPlisHSPlasH_PBF_TimeIntegration.h

Class Documentation

```
class SPH::TimeIntegration
```

Class for the position-based fluids time integration.

Public Static Functions

```
void semiImplicitEuler (const Real h, const Real mass, Vector3r &position, Vector3r &velocity, const Vector3r &acceleration)
```

Perform an integration step for a particle using the semi-implicit Euler (symplectic Euler) method:

$$\begin{aligned}\mathbf{v}(t + h) &= \mathbf{v}(t) + \mathbf{a}(t)h \\ \mathbf{x}(t + h) &= \mathbf{x}(t) + \mathbf{v}(t + h)h\end{aligned}$$

Parameters

- h: time step size
- mass: mass of the particle
- position: position of the particle
- velocity: velocity of the particle
- acceleration: acceleration of the particle

```
void velocityUpdateFirstOrder (const Real h, const Real mass, const Vector3r &position, const Vector3r &oldPosition, Vector3r &velocity)
```

Perform a velocity update (first order) for the linear velocity:

$$\mathbf{v}(t + h) = \frac{1}{h}(\mathbf{p}(t + h) - \mathbf{p}(t))$$

Parameters

- h: time step size

- **mass**: mass of the particle
- **position**: new position $\mathbf{p}(t + h)$ of the particle
- **oldPosition**: position $\mathbf{p}(t)$ of the particle before the time step
- **velocity**: resulting velocity of the particle

```
void velocityUpdateSecondOrder(const Real h, const Real mass, const Vector3r &position,
                            const Vector3r &oldPosition, const Vector3r &positionOfLastStep, Vector3r &velocity)
```

Class TimeManager

- Defined in file_SPlisHSPlasH_TimeManager.h

Class Documentation

class SPH::TimeManager

Class to manage the current simulation time and the time step size. This class is a singleton.

Public Functions

```
TimeManager ()
~TimeManager ()

Real getTime ()
void setTime (Real t)
Real getTimeStepSize ()
void  setTimeStepSize (Real tss)
void saveState (BinaryFileWriter &binWriter)
void loadState (BinaryFileReader &binReader)
```

Public Static Functions

```
TimeManager *getCurrent ()
void setCurrent (TimeManager *tm)
bool hasCurrent ()
```

Class TimeStep

- Defined in file_SPlisHSPlasH_TimeStep.h

Inheritance Relationships

Base Type

- public ParameterObject

Derived Types

- public SPH::TimeStepDFSPH (*Class TimeStepDFSPH*)
- public SPH::TimeStepIISPH (*Class TimeStepIISPH*)
- public SPH::TimeStepPBF (*Class TimeStepPBF*)
- public SPH::TimeStepPCISPH (*Class TimeStepPCISPH*)
- public SPH::TimeStepPF (*Class TimeStepPF*)
- public SPH::TimeStepWCSPH (*Class TimeStepWCSPH*)

Class Documentation

```
class SPH::TimeStep : public ParameterObject
```

Base class for the simulation methods.

Subclassed by *SPH::TimeStepDFSPH*, *SPH::TimeStepIISPH*, *SPH::TimeStepPBF*, *SPH::TimeStepPCISPH*, *SPH::TimeStepPF*, *SPH::TimeStepWCSPH*

Public Functions

```
TimeStep()
~TimeStep(void)
void step() = 0
void reset()
void init()
void resize() = 0
void emittedParticles(FluidModel *model, const unsigned int startIndex)
void saveState(BinaryFileWriter &binWriter)
void loadState(Binary.FileReader &binReader)
```

Public Static Attributes

```
int SOLVER_ITERATIONS = -1
int MIN_ITERATIONS = -1
int MAX_ITERATIONS = -1
int MAX_ERROR = -1
```

Protected Functions

```
void clearAccelerations (const unsigned int fluidModelIndex)
    Clear accelerations and add gravitation.

void computeDensities (const unsigned int fluidModelIndex)
    Determine densities of all fluid particles.

void initParameters ()

void approximateNormal (Discregrid::DiscreteGrid *map, const Eigen::Vector3d &x, Vector3r &n, const unsigned int dim)
void computeVolumeAndBoundaryX (const unsigned int fluidModelIndex, const unsigned int i,
                                const Vector3r &xi)
void computeVolumeAndBoundaryX ()
void computeDensityAndGradient (const unsigned int fluidModelIndex, const unsigned int i,
                                const Vector3r &xi)
void computeDensityAndGradient ()
```

Protected Attributes

```
unsigned int m_iterations
Real m_maxError
unsigned int m_minIterations
unsigned int m_maxIterations
```

Class TimeStepDFSPH

- Defined in file_SPlisHSPlasH_DFSPh_TimeStepDFSPH.h

Inheritance Relationships

Base Type

- public SPH::TimeStep (*Class TimeStep*)

Class Documentation

```
class SPH::TimeStepDFSPH : public SPH::TimeStep
```

This class implements the Divergence-free Smoothed Particle Hydrodynamics approach introduced by Bender and Koschier [5], [6], [16].

Public Functions

```
TimeStepDFSPH()
~TimeStepDFSPH(void)
void step()
void reset()
void resize()
```

Public Static Attributes

```
int SOLVER_ITERATIONS_V = -1
int MAX_ITERATIONS_V = -1
int MAX_ERROR_V = -1
int USE_DIVERGENCE_SOLVER = -1
```

Protected Functions

```
void computeDFSPHFactor(const unsigned int fluidModelIndex)
void pressureSolve()
void pressureSolveIteration(const unsigned int fluidModelIndex, Real &avg_density_err)
void divergenceSolve()
void divergenceSolveIteration(const unsigned int fluidModelIndex, Real &avg_density_err)
void computeDensityAdv(const unsigned int fluidModelIndex, const unsigned int index, const
                      int numParticles, const Real h, const Real density0)
void computeDensityChange(const unsigned int fluidModelIndex, const unsigned int index,
                         const Real h)
void warmstartDivergenceSolve(const unsigned int fluidModelIndex)
void warmstartPressureSolve(const unsigned int fluidModelIndex)
void performNeighborhoodSearch()
    Perform the neighborhood search for all fluid particles.
void emittedParticles(FluidModel *model, const unsigned int startIndex)
void initParameters()
```

Protected Attributes

```
SimulationDataDFSPH m_simulationData
unsigned int m_counter
const Real m_eps = static_cast<Real>(1.0e-5)
bool m_enableDivergenceSolver
unsigned int m_iterationsV
Real m_maxErrorV
unsigned int m_maxIterationsV
```

Class TimeStepIISPH

- Defined in file_SPlisHSPlasH_IISPH_TimeStepIISPH.h

Inheritance Relationships

Base Type

- public SPH::TimeStep (*Class TimeStep*)

Class Documentation

`class SPH::TimeStepIISPH : public SPH::TimeStep`

This class implements the Implicit Incompressible SPH approach introduced by Ihmsen et al. [13].

Public Functions

```
TimeStepIISPH()
~TimeStepIISPH(void)
void step()
void reset()
void resize()
const SimulationDataIISPH &getSimulationData()
```

Protected Functions

```
void predictAdvection(const unsigned int fluidModelIndex)
void pressureSolve()
void pressureSolveIteration(const unsigned int fluidModelIndex, Real &avg_density_err)
void integration(const unsigned int fluidModelIndex)
void computePressureAccels(const unsigned int fluidModelIndex)
Determine the pressure accelerations when the pressure is already known.
```

```
void performNeighborhoodSearch ()
    Perform the neighborhood search for all fluid particles.

void emittedParticles (FluidModel *model, const unsigned int startIndex)
```

Protected Attributes

```
SimulationDataIISPH m_simulationData
unsigned int m_counter
```

Class TimeStepPBF

- Defined in file_SPlisHSPlasH_PBF_TimeStepPBF.h

Inheritance Relationships

Base Type

- public SPH::TimeStep (*Class TimeStep*)

Class Documentation

```
class SPH::TimeStepPBF : public SPH::TimeStep
```

This class implements the position-based fluids approach introduced by Macklin and Mueller [17], [7], [8].

Public Functions

```
TimeStepPBF ()
    Initialize the simulation data required for this method.

~TimeStepPBF (void)

void step ()
    Perform a simulation step.

void reset ()
    Reset the simulation method.

void resize ()
```

Public Static Attributes

```
int VELOCITY_UPDATE_METHOD = -1
int ENUM_PBF_FIRST_ORDER = -1
int ENUM_PBF_SECOND_ORDER = -1
```

Protected Functions

```
void pressureSolve ()
    Perform a position-based correction step for the following density constraint: $C(\mathbf{x}) = \left( \frac{\rho_i}{\rho_0} - 1 \right) = 0$ 
void pressureSolveIteration (const unsigned int fluidModelIndex, Real &avg_density_err)
void performNeighborhoodSearch ()
    Perform the neighborhood search for all fluid particles.
void emittedParticles (FluidModel *model, const unsigned int startIndex)
void initParameters ()
```

Protected Attributes

```
SimulationDataPBF m_simulationData
unsigned int m_counter
int m_velocityUpdateMethod
```

Class TimeStepPCISPH

- Defined in file_SPlisHSPlasH_PCISPH_TimeStepPCISPH.h

Inheritance Relationships

Base Type

- public SPH::TimeStep (*Class TimeStep*)

Class Documentation

```
class SPH::TimeStepPCISPH : public SPH::TimeStep
```

This class implements the Predictive-corrective Incompressible SPH approach introduced by Solenthaler and Pajarola [23].

Public Functions

```
TimeStepPCISPH ()
~TimeStepPCISPH (void)
void step ()
void reset ()
void resize ()
```

Protected Functions

```
void pressureSolve()  
void pressureSolveIteration (const unsigned int fluidModelIndex, Real &avg_density_err)  
void performNeighborhoodSearch()  
    Perform the neighborhood search for all fluid particles.  
void emittedParticles (FluidModel *model, const unsigned int startIndex)
```

Protected Attributes

```
SimulationDataPCISPH m_simulationData  
unsigned int m_counter
```

Class TimeStepPF

- Defined in file_SPlisHSPlasH_PF_TimeStepPF.h

Inheritance Relationships

Base Type

- public SPH::TimeStep (*Class TimeStep*)

Class Documentation

```
class SPH::TimeStepPF : public SPH::TimeStep
```

This class implements the Projective Fluids approach introduced by Weiler, Koschier and Bender [25].

Public Functions

```
TimeStepPF ()  
~TimeStepPF (void)  
void step () override  
void reset () override  
void resize () override
```

Public Static Functions

```
void matrixVecProd(const Real *vec, Real *result, void *userData)
```

Public Static Attributes

```
int STIFFNESS = -1
```

Protected Types

```
using VectorXr = Eigen::Matrix<Real, -1, 1>
using VectorXrMap = Eigen::Map<VectorXr>
using Solver = Eigen::ConjugateGradient<MatrixReplacement, Eigen::Lower | Eigen::Upper, JacobiPreconditioner3D>
```

Protected Functions

```
void preparePreconditioner()
void initialGuessForPositions(const unsigned int fluidModelIndex)
void solvePDConstraints()
void updatePositionsAndVelocity(const VectorXr &x)
void addAccelerationToVelocity()
void matrixFreeRHS(const VectorXr &x, VectorXr &result)
    compute the right hand side of the system in a matrix-free fashion and store the result in result
void performNeighborhoodSearch()
    Perform the neighborhood search for all fluid particles.
void emittedParticles(FluidModel *model, const unsigned int startIndex) override
void initParameters() override
```

Protected Attributes

```
SimulationDataPF m_simulationData
Solver m_solver
Real m_stiffness
unsigned int m_counter
unsigned int m_numActiveParticlesTotal
```

Protected Static Functions

```
FORCE_INLINE void diagonalMatrixElement (const unsigned int row, Vector3r &result, voi
```

Class TimeStepWCSPH

- Defined in file_SPlisHSPlasH_WCSPH_TimeStepWCSPH.h

Inheritance Relationships

Base Type

- public SPH::TimeStep (*Class TimeStep*)

Class Documentation

```
class SPH::TimeStepWCSPH : public SPH::TimeStep
```

This class implements the Weakly Compressible SPH for Free Surface Flows approach introduced by Becker and Teschner [3].

Public Functions

```
TimeStepWCSPH ()  
~TimeStepWCSPH (void)  
void step ()  
void reset ()  
void resize ()
```

Public Static Attributes

```
int STIFFNESS = -1
```

```
int EXPONENT = -1
```

Protected Functions

```
void computePressureAccels (const unsigned int fluidModelIndex)
```

Determine the pressure accelerations when the pressure is already known.

```
void performNeighborhoodSearch ()
```

Perform the neighborhood search for all fluid particles.

```
void emittedParticles (FluidModel *model, const unsigned int startIndex)
```

```
void initParameters ()
```

Protected Attributes

```
Real m_stiffness
Real m_exponent
SimulationDataWCSPH m_simulationData
unsigned int m_counter
```

Class TriangleMesh

- Defined in file_SPlisHSPlasH_TriangleMesh.h

Class Documentation

```
class SPH::TriangleMesh
```

Data structure for a triangle mesh with normals and vertex normals.

Public Types

```
typedef std::vector<unsigned int> Faces
typedef std::vector<Vector3r> Normals
typedef std::vector<Vector3r> Vertices
```

Public Functions

```
TriangleMesh()
~TriangleMesh()
void release()
void initMesh(const unsigned int nPoints, const unsigned int nFaces)
void addFace(const unsigned int *const indices)
    Add a new face.
void addFace(const int *const indices)
    Add a new face.
void addVertex(const Vector3r &vertex)
    Add new vertex.
const Faces &getFaces() const
Faces &getFaces()
const Normals &getFaceNormals() const
Normals &getFaceNormals()
const Normals &getVertexNormals() const
Normals &getVertexNormals()
const Vertices &getVertices() const
```

```
Vertices &getVertices()
unsigned int numVertices() const
unsigned int numFaces() const
void updateNormals()
void updateVertexNormals()
```

Protected Attributes

```
Vertices m_x
Faces m_indices
Normals m_normals
Normals m_vertexNormals
```

Class Viscosity_Bender2017

- Defined in file_SPlisHSPlasH_Viscosity_Viscosity_Bender2017.h

Inheritance Relationships

Base Type

- public SPH::ViscosityBase (*Class ViscosityBase*)

Class Documentation

```
class SPH::Viscosity_Bender2017 : public SPH::ViscosityBase
```

This class implements the implicit simulation method for viscous fluids introduced by Bender and Koschier [6].

Public Functions

```
Viscosity_Bender2017 (FluidModel *model)
~Viscosity_Bender2017 (void)
void step ()
void reset ()
void performNeighborhoodSearchSort ()
void computeTargetStrainRate ()
void computeViscosityFactor ()

FORCE_INLINE void viscoGradientMultTransposeRightOpt (const Eigen::Matrix< Real, 6, 3 >
    Matrix product

FORCE_INLINE const Vector6r & getTargetStrainRate (const unsigned int i) const
FORCE_INLINE Vector6r & getTargetStrainRate (const unsigned int i)
```

```
FORCE_INLINE void setTargetStrainRate (const unsigned int i, const Vector6r &val)
FORCE_INLINE const Matrix6r & getViscosityFactor (const unsigned int i) const
FORCE_INLINE Matrix6r & getViscosityFactor (const unsigned int i)
FORCE_INLINE void setViscosityFactor (const unsigned int i, const Matrix6r &val)
FORCE_INLINE const Vector6r & getViscosityLambda (const unsigned int i) const
FORCE_INLINE Vector6r & getViscosityLambda (const unsigned int i)
FORCE_INLINE void setViscosityLambda (const unsigned int i, const Vector6r &val)
```

Public Static Attributes

```
int ITERATIONS = -1
int MAX_ITERATIONS = -1
int MAX_ERROR = -1
```

Protected Functions

```
void initParameters ()
```

Protected Attributes

```
std::vector<Vector6r> m_targetStrainRate
std::vector<Matrix6r> m_viscosityFactor
std::vector<Vector6r> m_viscosityLambda
unsigned int m_iterations
unsigned int m_maxIter
Real m_maxError
```

Class Viscosity_Peer2015

- Defined in file_SPlisHSPlasH_Viscosity_Viscosity_Peer2015.h

Inheritance Relationships

Base Type

- public SPH::ViscosityBase (*Class ViscosityBase*)

Class Documentation

```
class SPH::Viscosity_Peer2015 : public SPH::ViscosityBase
```

This class implements the implicit simulation method for viscous fluids introduced by Peer et al. [20].

Public Functions

```
Viscosity_Peer2015 (FluidModel *model)
~Viscosity_Peer2015 (void)
void step ()
void reset ()
void performNeighborhoodSearchSort ()
FORCE_INLINE const Matrix3r & getTargetNablaV (const unsigned int i) const
FORCE_INLINE Matrix3r & getTargetNablaV (const unsigned int i)
FORCE_INLINE void setTargetNablaV (const unsigned int i, const Matrix3r &val)
```

Public Static Functions

```
void matrixVecProd (const Real *vec, Real *result, void *userData)
```

```
FORCE_INLINE void diagonalMatrixElement (const unsigned int row, Real &result, void *u
```

Public Static Attributes

```
int ITERATIONS = -1
```

```
int MAX_ITERATIONS = -1
```

```
int MAX_ERROR = -1
```

Protected Types

```
typedef Eigen::ConjugateGradient<MatrixReplacement, Eigen::Lower | Eigen::Upper, JacobiPreconditionerID> Solver
```

Protected Functions

```
void initParameters ()
```

```
void computeDensities ()
```

Protected Attributes

```
std::vector<Real> m_density
std::vector<Matrix3r> m_targetNablaV
Solver m_solver
unsigned int m_iterations
unsigned int m_maxIter
Real m_maxError
```

Class Viscosity_Peer2016

- Defined in file_SPlisHSPlasH_Viscosity_Viscosity_Peer2016.h

Inheritance Relationships

Base Type

- public SPH::ViscosityBase (*Class ViscosityBase*)

Class Documentation

```
class SPH::Viscosity_Peer2016 : public SPH::ViscosityBase
```

This class implements the implicit simulation method for viscous fluids introduced by Peer and Teschner [19].

Public Functions

```
Viscosity_Peer2016(FluidModel *model)
~Viscosity_Peer2016(void)

void step()
void reset()

void performNeighborhoodSearchSort()

FORCE_INLINE const Matrix3r & getTargetNablaV (const unsigned int i) const
FORCE_INLINE Matrix3r & getTargetNablaV (const unsigned int i)
FORCE_INLINE void setTargetNablaV (const unsigned int i, const Matrix3r &val)
FORCE_INLINE const Vector3r & getOmega (const unsigned int i) const
FORCE_INLINE Vector3r & getOmega (const unsigned int i)
FORCE_INLINE void setOmega (const unsigned int i, const Vector3r &val)
```

Public Static Functions

```
void matrixVecProdV (const Real *vec, Real *result, void *userData)
FORCE_INLINE void diagonalMatrixElementV (const unsigned int row, Real &result, void *
void matrixVecProdOmega (const Real *vec, Real *result, void *userData)
FORCE_INLINE void diagonalMatrixElementOmega (const unsigned int row, Real &result, void *
```

Public Static Attributes

```
int ITERATIONS_V = -1
int ITERATIONS_OMEGA = -1
int MAX_ITERATIONS_V = -1
int MAX_ERROR_V = -1
int MAX_ITERATIONS_OMEGA = -1
int MAX_ERROR_OMEGA = -1
```

Protected Types

```
typedef Eigen::ConjugateGradient<MatrixReplacement, Eigen::Lower | Eigen::Upper, JacobiPreconditionerID> Solver
```

Protected Functions

```
void initParameters ()
void computeDensities ()
```

Protected Attributes

```
std::vector<Real> m_density
std::vector<Matrix3r> m_targetNablaV
std::vector<Vector3r> m_omega
Solver m_solverV
Solver m_solverOmega
unsigned int m_iterationsV
unsigned int m_iterationsOmega
unsigned int m_maxIterV
Real m_maxErrorV
unsigned int m_maxIterOmega
Real m_maxErrorOmega
```

Class Viscosity_Standard

- Defined in file_SPlisHSPlasH_Viscosity_Viscosity_Standard.h

Inheritance Relationships

Base Type

- public SPH::ViscosityBase (*Class ViscosityBase*)

Class Documentation

```
class SPH::Viscosity_Standard : public SPH::ViscosityBase
```

This class implements the standard method for viscosity described e.g. by Ihmsen et al. [14]. The method evaluates the term $\nu \nabla^2 v$ and uses an approximation of the kernel Laplacian to improve the stability. This approximation is given in [14].

Public Functions

```
Viscosity_Standard(FluidModel *model)
~Viscosity_Standard(void)
void step()
void reset()
```

Public Static Attributes

```
int VISCOSITY_COEFFICIENT_BOUNDARY = -1
```

Protected Functions

```
void initParameters()
```

Protected Attributes

```
Real m_boundaryViscosity
```

Class Viscosity_Takahashi2015

- Defined in file_SPlisHSPlasH_Viscosity_Viscosity_Takahashi2015.h

Inheritance Relationships

Base Type

- public SPH::ViscosityBase (*Class ViscosityBase*)

Class Documentation

```
class SPH::Viscosity_Takahashi2015 : public SPH::ViscosityBase
```

This class implements a variant of the implicit simulation method for viscous fluids introduced by Takahashi et al. [24]. In the original work of Takahashi et al. the second-ring neighbors are required to create the matrix of the linear system. In contrast we use a meshless conjugate gradient solver which performs the required matrix-vector multiplication in two sequential loops. In this way only the one-ring neighbors are required in each loop which increases the performance significantly. Thanks to Anreas Peer who helped us with the implementation.

Public Functions

```
Viscosity_Takahashi2015 (FluidModel *model)  
~Viscosity_Takahashi2015 (void)  
void step ()  
void reset ()  
void performNeighborhoodSearchSort ()  
FORCE_INLINE const Matrix3r & getViscousStress (const unsigned int i) const  
FORCE_INLINE Matrix3r & getViscousStress (const unsigned int i)  
FORCE_INLINE void setViscousStress (const unsigned int i, const Matrix3r &val)  
FORCE_INLINE const Vector3r & getAccel (const unsigned int i) const  
FORCE_INLINE Vector3r & getAccel (const unsigned int i)  
FORCE_INLINE void setAccel (const unsigned int i, const Vector3r &val)
```

Public Static Functions

```
void matrixVecProd (const Real *vec, Real *result, void *userData)  
FORCE_INLINE void diagonalMatrixElement (const unsigned int row, Real &result, void *u
```

Public Static Attributes

```
int ITERATIONS = -1  
int MAX_ITERATIONS = -1  
int MAX_ERROR = -1
```

Protected Types

```
typedef Eigen::ConjugateGradient<MatrixReplacement, Eigen::Lower | Eigen::Upper, Eigen::IdentityPreconditioner> Solver
```

Protected Functions

```
void initParameters()
```

Protected Attributes

```
std::vector<Vector3r> m_accel
std::vector<Matrix3r> m_viscousStress
Solver m_solver
unsigned int m_iterations
unsigned int m_maxIter
Real m_maxError
```

Protected Static Functions

```
void computeViscosityAcceleration(Viscosity_Takahashi2015 *visco, const Real *v)
```

Class Viscosity_Weiler2018

- Defined in file_SPlisHSPlasH_Viscosity_Viscosity_Weiler2018.h

Inheritance Relationships

Base Type

- public SPH::ViscosityBase (*Class ViscosityBase*)

Class Documentation

```
class SPH::Viscosity_Weiler2018 : public SPH::ViscosityBase
```

This class implements the implicit Laplace viscosity method introduced by Weiler et al. 2018 [26].

Public Functions

```
Viscosity_Weiler2018 (FluidModel *model)
~Viscosity_Weiler2018 (void)
void step ()
void reset ()
void performNeighborhoodSearchSort ()
```

Public Static Functions

```
void matrixVecProd(const Real *vec, Real *result, void *userData)
```

Public Static Attributes

```
int ITERATIONS = -1  
int MAX_ITERATIONS = -1  
int MAX_ERROR = -1  
int VISCOSITY_COEFFICIENT_BOUNDARY = -1
```

Protected Types

```
typedef Eigen::ConjugateGradient<MatrixReplacement, Eigen::Lower | Eigen::Upper, BlockJacobiPreconditioner3D> Solver
```

Protected Functions

```
void initParameters()
```

Protected Attributes

```
Real m_boundaryViscosity  
unsigned int m_maxIter  
Real m_maxError  
unsigned int m_iterations  
std::vector<Vector3r> m_vDiff  
Solver m_solver
```

Protected Static Functions

```
FORCE_INLINE void diagonalMatrixElement (const unsigned int row, Matrix3r &result, void *userData)
```

Class Viscosity_XSPH

- Defined in file_SPlisHSPlasH_Viscosity_Viscosity_XSPH.h

Inheritance Relationships

Base Type

- public SPH::ViscosityBase (*Class ViscosityBase*)

Class Documentation

class SPH::Viscosity_XSPH : **public** SPH::ViscosityBase

This class implements the XSPH method described by Schechter and Bridson [22].

Public Functions

```
Viscosity_XSPH (FluidModel *model)
~Viscosity_XSPH (void)
void step ()
void reset ()
```

Public Static Attributes

```
int VISCOSITY_COEFFICIENT_BOUNDARY = -1
```

Protected Functions

```
void initParameters ()
```

Protected Attributes

```
Real m_boundaryViscosity
```

Class ViscosityBase

- Defined in file_SPlisHSPlasH_Viscosity_ViscosityBase.h

Inheritance Relationships

Base Type

- public SPH::NonPressureForceBase (*Class NonPressureForceBase*)

Derived Types

- public SPH::Viscosity_Bender2017 (*Class Viscosity_Bender2017*)
- public SPH::Viscosity_Peer2015 (*Class Viscosity_Peer2015*)
- public SPH::Viscosity_Peer2016 (*Class Viscosity_Peer2016*)
- public SPH::Viscosity_Standard (*Class Viscosity_Standard*)
- public SPH::Viscosity_Takahashi2015 (*Class Viscosity_Takahashi2015*)
- public SPH::Viscosity_Weiler2018 (*Class Viscosity_Weiler2018*)
- public SPH::Viscosity_XSPH (*Class Viscosity_XSPH*)

Class Documentation

```
class SPH::ViscosityBase : public SPH::NonPressureForceBase
    Base class for all viscosity methods.
```

Subclassed by *SPH::Viscosity_Bender2017*, *SPH::Viscosity_Peer2015*, *SPH::Viscosity_Peer2016*, *SPH::Viscosity_Standard*, *SPH::Viscosity_Takahashi2015*, *SPH::Viscosity_Weiler2018*, *SPH::Viscosity_XSPH*

Public Functions

```
ViscosityBase(FluidModel *model)
~ViscosityBase(void)
```

Public Static Attributes

```
int VISCOSITY_COEFFICIENT = -1
```

Protected Functions

```
void initParameters()
```

Protected Attributes

```
Real m_viscosity
```

Class VorticityBase

- Defined in file_SPlisHSPlasH_Vorticity_VorticityBase.h

Inheritance Relationships

Base Type

- public SPH::NonPressureForceBase (*Class NonPressureForceBase*)

Derived Types

- public SPH::MicropolarModel_Bender2017 (*Class MicropolarModel_Bender2017*)
- public SPH::VorticityConfinement (*Class VorticityConfinement*)

Class Documentation

class SPH::VorticityBase : **public** SPH::NonPressureForceBase
Base class for all vorticity methods.

Subclassed by *SPH::MicropolarModel_Bender2017, SPH::VorticityConfinement*

Public Functions

VorticityBase (*FluidModel* **model*)
~VorticityBase (void)

Public Static Attributes

int **VORTICITY_COEFFICIENT** = -1

Protected Functions

void **initParameters** ()

Protected Attributes

Real **m_vorticityCoeff**

Class VorticityConfinement

- Defined in file_SPlisHSPlasH_Vorticity_VorticityConfinement.h

Inheritance Relationships

Base Type

- public SPH::VorticityBase (*Class VorticityBase*)

Class Documentation

```
class SPH::VorticityConfinement : public SPH::VorticityBase
```

This class implements the vorticity confinement method introduced by Macklin and Mueller [17].

Public Functions

```
VorticityConfinement (FluidModel *model)
~VorticityConfinement (void)
void step ()
void reset ()
void performNeighborhoodSearchSort ()
FORCE_INLINE const Vector3r & getAngularVelocity (const unsigned int i) const
FORCE_INLINE Vector3r & getAngularVelocity (const unsigned int i)
FORCE_INLINE void setAngularVelocity (const unsigned int i, const Vector3r &val)
```

Protected Attributes

```
std::vector<Vector3r> m_omega
std::vector<Real> m_normOmega
```

Class WendlandQuinticC2Kernel

- Defined in file_SPlisHSPlasH_SPHKernels.h

Class Documentation

```
class SPH::WendlandQuinticC2Kernel
quintic Wendland C2 kernel.
```

Public Static Functions

```
Real getRadius ()
void setRadius (Real val)
Real W (const Real r)
Real W (const Vector3r &r)
Vector3r gradW (const Vector3r &r)
Real W_zero ()
```

Protected Static Attributes

```
Real m_radius
Real m_k
Real m_l
Real m_W_zero
```

Class WendlandQuinticC2Kernel2D

- Defined in file_SPlisHSPlasH_SPHKernels.h

Class Documentation

```
class SPH::WendlandQuinticC2Kernel2D
Wendland Quintic C2 spline kernel (2D).
```

Public Static Functions

```
Real getRadius ()
void setRadius (Real val)
Real W (const Real r)
Real W (const Vector3r &r)
Vector3r gradW (const Vector3r &r)
Real W_zero ()
```

Protected Static Attributes

Real `m_radius`
Real `m_k`
Real `m_l`
Real `m_W_zero`

Class SceneLoader

- Defined in file_SPlisHSPlasH_Utilsities_SceneLoader.h

Nested Relationships

Nested Types

- Struct* `SceneLoader::AnimationFieldData`
- Struct* `SceneLoader::BoundaryData`
- Struct* `SceneLoader::Box`
- Struct* `SceneLoader::EmitterData`
- Struct* `SceneLoader::FluidBlock`
- Struct* `SceneLoader::FluidData`
- Struct* `SceneLoader::MaterialData`
- Struct* `SceneLoader::Scene`

Class Documentation

```
class Utilities::SceneLoader
    Importer of SPlisHSPlasH scene files.
```

Public Functions

```
void readScene (const char *fileName, Scene &scene)
template<typename T>
bool readValue (const nlohmann::json &j, T &v)
template<typename T, int sizereadVector (const nlohmann::json &j, Eigen::Matrix<T, size, 1, Eigen::DontAlign> &vec)
template<typename T>
bool readValue (const std::string &section, const std::string &key, T &v)
template<typename T, int sizereadVector (const std::string &section, const std::string &key, Eigen::Matrix<T, size, 1,
                Eigen::DontAlign> &vec)
void readMaterialParameterObject (const std::string &key, GenParam::ParameterObject
                                *paramObj)
```

```
void readParameterObject (const std::string &key, GenParam::ParameterObject *paramObj)
template<>
bool readValue (const nlohmann::json &j, bool &v)
template<>
bool readValue (const nlohmann::json &j, bool &v)
```

Protected Functions

```
void readParameterObject (nlohmann::json &config, GenParam::ParameterObject *paramObj)
```

Protected Attributes

```
nlohmann::json m_jsonData
struct AnimationFieldData
Struct to store an animation field object.
```

Public Members

```
std::string particleFieldName
std::string expression[3]
unsigned int shapeType
Vector3r x
Matrix3r rotation
Vector3r scale
Real startTime
Real endTime
struct BoundaryData
Struct to store a boundary object.
```

Public Members

```
std::string samplesFile
std::string meshFile
Vector3r translation
Matrix3r rotation
Vector3r scale
Real density
bool dynamic
bool isWall
Eigen::Matrix<float, 4, 1, Eigen::DontAlign> color
void *rigidBody
```

```
std::string mapFile
bool mapInvert
Real mapThickness
Eigen::Matrix<unsigned int, 3, 1, Eigen::DontAlign> mapResolution
unsigned int samplingMode

struct Box
    Struct for an AABB.
```

Public Members

```
Vector3r m_minX
Vector3r m_maxX

struct EmitterData
    Struct to store an emitter object.
```

Public Members

```
std::string id
unsigned int width
unsigned int height
Vector3r x
Real velocity
Matrix3r rotation
Real emitStartTime
Real emitEndTime
unsigned int type

struct FluidBlock
    Struct to store a fluid block.
```

Public Members

```
std::string id
Box box
unsigned char mode
Vector3r initialVelocity

struct FluidData
    Struct to store a fluid object.
```

Public Members

```
std::string id
std::string samplesFile
Vector3r translation
Matrix3r rotation
Vector3r scale
Vector3r initialVelocity
unsigned char mode
bool invert
std::array<unsigned int, 3> resolutionSDF

struct MaterialData
    Struct to store particle coloring information.
```

Public Members

```
std::string id
std::string colorField
unsigned int colorMapType
Real minVal
Real maxVal
unsigned int maxEmitterParticles
bool emitterReuseParticles
Vector3r emitterBoxMin
Vector3r emitterBoxMax

struct Scene
    Struct to store scene information.
```

Public Members

```
std::vector<BoundaryData*> boundaryModels
std::vector<FluidData*> fluidModels
std::vector<FluidBlock*> fluidBlocks
std::vector<EmitterData*> emitters
std::vector<AnimationFieldData*> animatedFields
std::vector<MaterialData*> materials
Real particleRadius
bool sim2D
Real timeStepSize
```

Vector3r **camPosition**

Vector3r **camLookat**

Class SDFFunctions

- Defined in file_SPlisHSPlasH_Utilsies_SDFFunctions.h

Class Documentation

class Utilities::SDFFunctions

Functions for generating and querying an SDF.

Public Static Functions

Discregrid::CubicLagrangeDiscreteGrid ***generateSDF** (**const** unsigned int *numVertices*, **const** *Vector3r* **vertices*, **const** unsigned int *numFaces*, **const** unsigned int **faces*, **const** *AlignedBox3r* &*bbox*, **const** std::array<unsigned int, 3> &*resolution*, **const** bool *invert* = false)

Generate SDF from mesh.

AlignedBox3r **computeBoundingBox** (**const** unsigned int *numVertices*, **const** *Vector3r* **vertices*)

Compute the bounding box of a mesh.

double **distance** (Discregrid::CubicLagrangeDiscreteGrid **sdf*, **const** *Vector3r* &*x*, **const** *Real* *thickness*, *Vector3r* &*normal*, *Vector3r* &*nextSurfacePoint*)

Determine distance of a point *x* to the surface represented by the SDF and corresponding surface normal and next point on the surface.

double **distance** (Discregrid::CubicLagrangeDiscreteGrid **sdf*, **const** *Vector3r* &*x*, **const** *Real* *thickness*)

Determine distance of a point *x* to the surface represented by the SDF.

Class VolumeSampling

- Defined in file_SPlisHSPlasH_Utilsies_VolumeSampling.h

Class Documentation

class Utilities::VolumeSampling

This class implements a volume sampling of 3D models.

Public Static Functions

```
void sampleMesh (const unsigned int numVertices, const Vector3r *vertices, const unsigned
int numFaces, const unsigned int *faces, const Real radius, const Aligned-
Box3r *region, const std::array<unsigned int, 3> &resolution, const bool invert,
const unsigned int sampleMode, std::vector<Vector3r> &samples)
```

Performs the volume sampling with the respective parameters.

Parameters

- numVertices: number of vertices
- vertices: vertex data
- numFaces: number of faces
- faces: index list of faces
- radius: radius of sampled particles
- region: defines a subregion of the mesh to be sampled (nullptr if not used)
- resolution: resolution of the used SDF
- invert: defines if the mesh should be inverted and the outside is sampled
- sampleMode: 0=regular, 1=almost dense, 2=dense
- samples: sampled vertices that will be returned

Class WindingNumbers

- Defined in file_SPlisHSPlasH_Utils_WindingNumbers.h

Class Documentation

```
class Utilities::WindingNumbers
```

Public Static Functions

```
Real computeGeneralizedWindingNumber (const Vector3r &p, const Vector3r &a, const
Vector3r &b, const Vector3r &c)
```

Determine the winding number for a point p and a triangle abc.

```
Real computeGeneralizedWindingNumber (const Vector3r &p, const SPH::TriangleMesh
&mesh)
```

Determine the winding number of a point p in a triangle mesh.

Class Vector3f8

- Defined in file_SPlisHSPlasH_Utilsies_AVX_math.h

Class Documentation

```
class Vector3f8
```

Public Functions

```
Vector3f8()
Vector3f8(const bool)
Vector3f8(const Scalarf8 &x, const Scalarf8 &y, const Scalarf8 &z)
Vector3f8(const Scalarf8 &x)
Vector3f8(const Vector3f &x)
Vector3f8(const Vector3f &v0, const Vector3f &v1, const Vector3f &v2, const Vector3f
&v3, const Vector3f &v4, const Vector3f &v5, const Vector3f &v6, const Vector3f
&v7)
Vector3f8(Vector3f const *x)
void setZero()
Scalarf8 &operator[](int i)
const Scalarf8 &operator[](int i) const
Scalarf8 &x()
Scalarf8 &y()
Scalarf8 &z()
const Scalarf8 &x() const
const Scalarf8 &y() const
const Scalarf8 &z() const
Scalarf8 dot(const Vector3f8 &a) const
Scalarf8 operator*(const Vector3f8 &a) const
void cross(const Vector3f8 &a, const Vector3f8 &b)
const Vector3f8 operator%(const Vector3f8 &a) const
Vector3f8 &operator*=(const Scalarf8 &s)
const Vector3f8 operator/(const Scalarf8 &s) const
Vector3f8 &operator/=(const Scalarf8 &s)
Vector3f8 &operator-=(const Vector3f8 &a)
const Vector3f8 operator-() const
Scalarf8 squaredNorm() const
Scalarf8 norm() const
```

```
void normalize ()
void store (std::vector<Vector3r> &Vf) const
void store (Vector3r *Vf) const
```

Public Members

Scalarf8 **v**[3]

Public Static Functions

Vector3f8 **blend** (*Scalarf8* **const** &*c*, *Vector3f8* **const** &*a*, *Vector3f8* **const** &*b*)

6.3.3 Enums

Enum BoundaryHandlingMethods

- Defined in file_SPlisHSPlasH_Simulation.h

Enum Documentation

```
enum SPH::BoundaryHandlingMethods
Values:
enumerator Akinci2012 = 0
enumerator Koschier2017
enumerator Bender2019
enumerator NumSimulationMethods
```

Enum DragMethods

- Defined in file_SPlisHSPlasH_FluidModel.h

Enum Documentation

```
enum SPH::DragMethods
Values:
enumerator None = 0
enumerator Macklin2014
enumerator Gissler2017
enumerator NumDragMethods
```

Enum ElasticityMethods

- Defined in file_SPlisHSPlasH_FluidModel.h

Enum Documentation

```
enum SPH::ElasticityMethods
Values:
enumerator None = 0
enumerator Becker2009
enumerator Peer2018
enumerator NumElasticityMethods
```

Enum FieldType

- Defined in file_SPlisHSPlasH_FluidModel.h

Enum Documentation

```
enum SPH::FieldType
Values:
enumerator Scalar = 0
enumerator Vector3
enumerator Vector6
enumerator Matrix3
enumerator Matrix6
enumerator UInt
```

Enum ParticleState

- Defined in file_SPlisHSPlasH_FluidModel.h

Enum Documentation

```
enum SPH::ParticleState
Values:
enumerator Active = 0
enumerator AnimatedByEmitter
```

Enum SimulationMethods

- Defined in file_SPlisHSPlasH_Simulation.h

Enum Documentation

```
enum SPH::SimulationMethods
Values:
enumerator WCSPH = 0
enumerator PCISPH
enumerator PBF
enumerator IISPH
enumerator DFSPH
enumerator PF
enumerator NumSimulationMethods
```

Enum SurfaceSamplingMode

- Defined in file_SPlisHSPlasH_Utilsities_SurfaceSampling.h

Enum Documentation

```
enum SPH::SurfaceSamplingMode
Values:
enumerator PoissonDisk
enumerator RegularTriangle
enumerator Regular2D
```

Enum SurfaceTensionMethods

- Defined in file_SPlisHSPlasH_FluidModel.h

Enum Documentation

```
enum SPH::SurfaceTensionMethods
Values:
enumerator None = 0
enumerator Becker2007
enumerator Akinci2013
enumerator He2014
enumerator NumSurfaceTensionMethods
```

Enum ViscosityMethods

- Defined in file_SPlisHSPlasH_FluidModel.h

Enum Documentation

```
enum SPH::ViscosityMethods
```

Values:

```
enumerator None = 0
enumerator Standard
enumerator XSPH
enumerator Bender2017
enumerator Peer2015
enumerator Peer2016
enumerator Takahashi2015
enumerator Weiler2018
enumerator NumViscosityMethods
```

Enum VorticityMethods

- Defined in file_SPlisHSPlasH_FluidModel.h

Enum Documentation

```
enum SPH::VorticityMethods
```

Values:

```
enumerator None = 0
enumerator Micropolar
enumerator VorticityConfinement
enumerator NumVorticityMethods
```

6.3.4 Functions

Function abs

- Defined in file_SPlisHSPlasH_Utils_AVX_math.h

Function Documentation

Scalarf8 abs (Scalarf8 const &a)

Function blend

- Defined in file_SPlisHSPlasH_Utilsies_AVX_math.h

Function Documentation

Warning: doxygenfunction: Unable to resolve multiple matches for function “blend” with arguments (Scalarf8 const&, Scalarf8 const&, Scalarf8 const&) in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxyoutput/xml. Potential matches:

```
- Scalarf8 blend(Scalarf8 const &c, Scalarf8 const &a, Scalarf8 const &b)
- Vector3f8 blend(Scalarf8 const &c, Vector3f8 const &a, Vector3f8 const &b)
```

Template Function constant8f

- Defined in file_SPlisHSPlasH_Utilsies_AVX_math.h

Function Documentation

```
template<int i0, int i1, int i2, int i3, int i4, int i5, int i6, int i7>
__m256 constant8f()
```

Function convert_one

- Defined in file_SPlisHSPlasH_Utilsies_AVX_math.h

Function Documentation

*Scalarf8 convert_one (const unsigned int *idx, const Real *x, const unsigned char count = 8u)*

Function convert_zero(const unsigned int *, const Real *, const unsigned char)

- Defined in file_SPlisHSPlasH_Utilsies_AVX_math.h

Function Documentation

Warning: doxygenfunction: Unable to resolve multiple matches for function “convert_zero” with arguments (const unsigned int *, const Real *, const unsigned char) in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxyoutput/xml. Potential matches:

- Scalarf8 convert_zero(**const** Real x, **const unsigned char** count = 8u)
- Scalarf8 convert_zero(**const unsigned int** *idx, **const** Real *x, **const unsigned char** ↳count = 8u)

Function convert_zero(const Real, const unsigned char)

- Defined in file_SPlisHSPlasH_Utilsities_AVX_math.h

Function Documentation

Warning: doxygenfunction: Unable to resolve multiple matches for function “convert_zero” with arguments (const Real, const unsigned char) in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxyoutput/xml. Potential matches:

- Scalarf8 convert_zero(**const** Real x, **const unsigned char** count = 8u)
- Scalarf8 convert_zero(**const unsigned int** *idx, **const** Real *x, **const unsigned char** ↳count = 8u)

Function convertVec_zero(const unsigned int *, const Real *, const unsigned char)

- Defined in file_SPlisHSPlasH_Utilsities_AVX_math.h

Function Documentation

Warning: doxygenfunction: Unable to resolve multiple matches for function “convertVec_zero” with arguments (const unsigned int *, const Real *, const unsigned char) in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxyoutput/xml. Potential matches:

- Vector3f8 convertVec_zero(**const unsigned int** *idx, **const** Real *v, **const unsigned char** ↳count = 8u)
- Vector3f8 convertVec_zero(**const unsigned int** *idx, **const** Vector3r *v, **const unsigned char** ↳count = 8u)

Function convertVec_zero(const unsigned int *, const Vector3r *, const unsigned char)

- Defined in file_SPlisHSPlasH_Utilsities_AVX_math.h

Function Documentation

Warning: doxygenfunction: Unable to resolve multiple matches for function “convertVec_zero” with arguments (const unsigned int *, const Vector3r *, const unsigned char) in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxyoutput/xml. Potential matches:

- Vector3f8 convertVec_zero(**const unsigned int** *idx, **const Real** *v, **const unsigned char** count = 8u)
- Vector3f8 convertVec_zero(**const unsigned int** *idx, **const Vector3r** *v, **const unsigned char** count = 8u)

Function dyadicProduct

- Defined in file_SPlisHSPlasH_Utilsities_AVX_math.h

Function Documentation

```
void dyadicProduct (const Vector3f8 &a, const Vector3f8 &b, Matrix3f8 &res)
```

Function getTime

- Defined in file_SPlisHSPlasH_AnimationField.cpp

Function Documentation

```
Real SPH::TimeManager::getTime()
```

Function max

- Defined in file_SPlisHSPlasH_Utilsities_AVX_math.h

Function Documentation

```
Scalarf8 max (Scalarf8 const &a, Scalarf8 const &b)
```

Function operator!=

- Defined in file_SPlisHSPlasH_Utilsies_AVX_math.h

Function Documentation

`Scalarf8 operator!=(Scalarf8 const &a, Scalarf8 const &b)`

Function operator*(Scalarf8 const&, Scalarf8 const&)

- Defined in file_SPlisHSPlasH_Utilsies_AVX_math.h

Function Documentation

Warning: doxygenfunction: Unable to resolve multiple matches for function “operator*” with arguments (Scalarf8 const&, Scalarf8 const&) in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxygen-output/xml. Potential matches:

```
- Matrix3f8 operator*(const Matrix3f8 &b) const
- Matrix3f8 operator*(const Scalarf8 &b) const
- Scalarf8 operator*(Scalarf8 const &a, Scalarf8 const &b)
- Scalarf8 operator*(const Vector3f8 &a) const
- Vector3f8 operator*(Vector3f8 const &a, const Scalarf8 &s)
- Vector3f8 operator*(const Vector3f8 &b) const
- const Quaternion8f operator*(const Quaternion8f &a) const
- template<typename Rhs> Eigen::Product<MatrixReplacement, Rhs, 
→Eigen::AliasFreeProduct> operator*(const Eigen::MatrixBase<Rhs> &x) const
```

Function operator*(Vector3f8 const&, const Scalarf8&)

- Defined in file_SPlisHSPlasH_Utilsies_AVX_math.h

Function Documentation

Warning: doxygenfunction: Unable to resolve multiple matches for function “operator*” with arguments (Vector3f8 const&, const Scalarf8&) in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxygen-output/xml. Potential matches:

```
- Matrix3f8 operator*(const Matrix3f8 &b) const
- Matrix3f8 operator*(const Scalarf8 &b) const
- Scalarf8 operator*(Scalarf8 const &a, Scalarf8 const &b)
- Scalarf8 operator*(const Vector3f8 &a) const
- Vector3f8 operator*(Vector3f8 const &a, const Scalarf8 &s)
- Vector3f8 operator*(const Vector3f8 &b) const
- const Quaternion8f operator*(const Quaternion8f &a) const
- template<typename Rhs> Eigen::Product<MatrixReplacement, Rhs, 
→Eigen::AliasFreeProduct> operator*(const Eigen::MatrixBase<Rhs> &x) const
```

Function operator*=¹

- Defined in file_SPlisHSPlasH_Utilsities_AVX_math.h

Function Documentation

Warning: doxygenfunction: Unable to resolve multiple matches for function “operator*=” with arguments (Scalarf8&, Scalarf8 const&) in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxyoutput/xml. Potential matches:

- Scalarf8 &**operator***=(Scalarf8 &a, Scalarf8 **const** &b)
- Vector3f8 &**operator***=(**const** Scalarf8 &s)

Function operator+(Scalarf8 const&, Scalarf8 const&)

- Defined in file_SPlisHSPlasH_Utilsities_AVX_math.h

Function Documentation

Warning: doxygenfunction: Unable to resolve multiple matches for function “operator+” with arguments (Scalarf8 const&, Scalarf8 const&) in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxyoutput/xml. Potential matches:

- Scalarf8 **operator**+(Scalarf8 **const** &a, Scalarf8 **const** &b)
- Vector3f8 **operator**+(Vector3f8 **const** &a, Vector3f8 **const** &b)

Function operator+(Vector3f8 const&, Vector3f8 const&)

- Defined in file_SPlisHSPlasH_Utilsities_AVX_math.h

Function Documentation

Warning: doxygenfunction: Unable to resolve multiple matches for function “operator+” with arguments (Vector3f8 const&, Vector3f8 const&) in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxyoutput/xml. Potential matches:

- Scalarf8 **operator**+(Scalarf8 **const** &a, Scalarf8 **const** &b)
- Vector3f8 **operator**+(Vector3f8 **const** &a, Vector3f8 **const** &b)

Function operator+=(Scalarf8&, Scalarf8 const&)

- Defined in file_SPlisHSPlasH_Utilsities_AVX_math.h

Function Documentation

Warning: doxygenfunction: Unable to resolve multiple matches for function “operator+=” with arguments (Scalarf8&, Scalarf8 const&) in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxyoutput/xml. Potential matches:

- Matrix3f8 &**operator**+=(**const** Matrix3f8 &a)
- Scalarf8 &**operator**+=(Scalarf8 &a, Scalarf8 **const** &b)
- Vector3f8 &**operator**+=(Vector3f8 &a, Vector3f8 **const** &b)

Function operator+=(Vector3f8&, Vector3f8 const&)

- Defined in file_SPlisHSPlasH_Utilsities_AVX_math.h

Function Documentation

Warning: doxygenfunction: Unable to resolve multiple matches for function “operator+=” with arguments (Vector3f8&, Vector3f8 const&) in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxyoutput/xml. Potential matches:

- Matrix3f8 &**operator**+=(**const** Matrix3f8 &a)
- Scalarf8 &**operator**+=(Scalarf8 &a, Scalarf8 **const** &b)
- Vector3f8 &**operator**+=(Vector3f8 &a, Vector3f8 **const** &b)

Function operator-(Scalarf8&)

- Defined in file_SPlisHSPlasH_Utilsities_AVX_math.h

Function Documentation

Warning: doxygenfunction: Unable to resolve multiple matches for function “operator-” with arguments (Scalarf8&) in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxyoutput/xml. Potential matches:

- Scalarf8 **operator**-(Scalarf8 &a)
- Scalarf8 **operator**-(Scalarf8 **const** &a, Scalarf8 **const** &b)
- Vector3f8 **operator**-(Vector3f8 **const** &a, Vector3f8 **const** &b)
- **const** Vector3f8 **operator**-() **const**

Function operator-(Scalarf8 const&, Scalarf8 const&)

- Defined in file_SPlisHSPlasH_Utilsies_AVX_math.h

Function Documentation

Warning: doxygenfunction: Unable to resolve multiple matches for function “operator-” with arguments (Scalarf8 const&, Scalarf8 const&) in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxygenoutput/xml. Potential matches:

- Scalarf8 **operator-**(Scalarf8 &a)
- Scalarf8 **operator-**(Scalarf8 **const** &a, Scalarf8 **const** &b)
- Vector3f8 **operator-**(Vector3f8 **const** &a, Vector3f8 **const** &b)
- **const** Vector3f8 **operator-**() **const**

Function operator-(Vector3f8 const&, Vector3f8 const&)

- Defined in file_SPlisHSPlasH_Utilsies_AVX_math.h

Function Documentation

Warning: doxygenfunction: Unable to resolve multiple matches for function “operator-” with arguments (Vector3f8 const&, Vector3f8 const&) in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxygenoutput/xml. Potential matches:

- Scalarf8 **operator-**(Scalarf8 &a)
- Scalarf8 **operator-**(Scalarf8 **const** &a, Scalarf8 **const** &b)
- Vector3f8 **operator-**(Vector3f8 **const** &a, Vector3f8 **const** &b)
- **const** Vector3f8 **operator-**() **const**

Function operator=

- Defined in file_SPlisHSPlasH_Utilsies_AVX_math.h

Function Documentation

Warning: doxygenfunction: Unable to resolve multiple matches for function “operator-=” with arguments (Scalarf8&, Scalarf8 const&) in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxygenoutput/xml. Potential matches:

- Scalarf8 &**operator-=(**Scalarf8 &a, Scalarf8 **const** &b)
- Vector3f8 &**operator-=(****const** Vector3f8 &a)

Function operator/

- Defined in file_SPlisHSPlasH_Utilsities_AVX_math.h

Function Documentation

Warning: doxygenfunction: Unable to resolve multiple matches for function “operator/” with arguments (Scalarf8 const&, Scalarf8 const&) in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxygenoutput/xml. Potential matches:

- Scalarf8 **operator/**(Scalarf8 **const** &a, Scalarf8 **const** &b)
- **const** Vector3f8 **operator/**(**const** Scalarf8 &s) **const**

Function operator/=

- Defined in file_SPlisHSPlasH_Utilsities_AVX_math.h

Function Documentation

Warning: doxygenfunction: Unable to resolve multiple matches for function “operator/=” with arguments (Scalarf8&, Scalarf8 const&) in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxygenoutput/xml. Potential matches:

- Scalarf8 &**operator/**= (Scalarf8 &a, Scalarf8 **const** &b)
- Vector3f8 &**operator/**= (**const** Scalarf8 &s)

Function operator<

- Defined in file_SPlisHSPlasH_Utilsities_AVX_math.h

Function Documentation

Scalarf8 **operator<** (*Scalarf8 const* &*a*, *Scalarf8 const* &*b*)

Function operator<=

- Defined in file_SPlisHSPlasH_Utilsities_AVX_math.h

Function Documentation

Scalarf8 operator<= (Scalarf8 const &a, Scalarf8 const &b)

Function operator==

- Defined in file_SPlisHSPlasH_Utilsies_AVX_math.h

Function Documentation

Scalarf8 operator==(Scalarf8 const &a, Scalarf8 const &b)

Function operator>

- Defined in file_SPlisHSPlasH_Utilsies_AVX_math.h

Function Documentation

Scalarf8 operator> (Scalarf8 const &a, Scalarf8 const &b)

Function operator>=

- Defined in file_SPlisHSPlasH_Utilsies_AVX_math.h

Function Documentation

Scalarf8 operator>= (Scalarf8 const &a, Scalarf8 const &b)

6.3.5 Variables

Variable SPH::gaussian_abscissae_1

- Defined in file_SPlisHSPlasH_Utilsies_GaussQuadrature.cpp

Variable Documentation

double **const** SPH::gaussian_abscissae_1[101][51]

Variable SPH::gaussian_n_1

- Defined in file_SPlisHSPlasH_Utilsities_GaussQuadrature.cpp

Variable Documentation

```
unsigned int const SPH::gaussian_n_1[101]
```

Variable SPH::gaussian_weights_1

- Defined in file_SPlisHSPlasH_Utilsities_GaussQuadrature.cpp

Variable Documentation

```
double const SPH::gaussian_weights_1[101][51]
```

6.3.6 Defines

Define _USE_MATH_DEFINES

- Defined in file_SPlisHSPlasH_Drag_DragForce_Gissler2017.cpp

Define Documentation

```
_USE_MATH_DEFINES
```

Define _USE_MATH_DEFINES

- Defined in file_SPlisHSPlasH_SPHKernels.h

Define Documentation

```
_USE_MATH_DEFINES
```

Define _USE_MATH_DEFINES

- Defined in file_SPlisHSPlasH_Utilsities_PoissonDiskSampling.cpp

Define Documentation`_USE_MATH_DEFINES`**Define _USE_MATH_DEFINES**

- Defined in file_SPlisHSPlasH_Utils_WindingNumbers.cpp

Define Documentation`_USE_MATH_DEFINES`**Define compute_Vj**

- Defined in file_SPlisHSPlasH_FluidModel.h

Define Documentation`compute_Vj (fm_neighbor)`**Define compute_Vj_gradW**

- Defined in file_SPlisHSPlasH_FluidModel.h

Define Documentation`compute_Vj_gradW ()`**Define compute_Vj_gradW_samephase**

- Defined in file_SPlisHSPlasH_FluidModel.h

Define Documentation`compute_Vj_gradW_samephase ()`**Define compute_xj**

- Defined in file_SPlisHSPlasH_FluidModel.h

Define Documentation

`compute_xj (fm_neighbor, pid)`

Define forall_boundary_neighbors

- Defined in file_SPlisHSPlasH_Simulation.h

Define Documentation

`forall_boundary_neighbors (code)`

Loop over the boundary neighbors of all fluid phases. Simulation *sim and unsigned int fluidModelIndex must be defined.

Define forall_density_maps

- Defined in file_SPlisHSPlasH_Simulation.h

Define Documentation

`forall_density_maps (code)`

Loop over the boundary density maps. Simulation *sim, unsigned int nBoundaries and unsigned int fluidModelIndex must be defined.

Define forall_fluid_neighbors

- Defined in file_SPlisHSPlasH_Simulation.h

Define Documentation

`forall_fluid_neighbors (code)`

Loop over the fluid neighbors of all fluid phases. Simulation *sim and unsigned int fluidModelIndex must be defined.

Define forall_fluid_neighbors_in_same_phase

- Defined in file_SPlisHSPlasH_Simulation.h

Define Documentation

forall_fluid_neighbors_in_same_phase (*code*)

Loop over the fluid neighbors of the same fluid phase. Simulation *sim*, unsigned int *fluidModelIndex* and Fluid-Model *model* must be defined.

Define forall_volume_maps

- Defined in file_SPlisHSPlasH_Simulation.h

Define Documentation

forall_volume_maps (*code*)

Loop over the boundary volume maps. Simulation **sim*, unsigned int *nBoundaries* and unsigned int *fluidModelIndex* must be defined.

Define FORCE_INLINE

- Defined in file_SPlisHSPlasH_Common.h

Define Documentation

FORCE_INLINE

Define PD_USE_DIAGONAL_PRECONDITIONER

- Defined in file_SPlisHSPlasH_PF_TimeStepPF.h

Define Documentation

PD_USE_DIAGONAL_PRECONDITIONER

Define REAL_MAX

- Defined in file_SPlisHSPlasH_Common.h

Define Documentation

REAL_MAX

Define REAL_MIN

- Defined in file_SPlisHSPlasH_Common.h

Define Documentation

REAL_MIN

Define RealParameter

- Defined in file_SPlisHSPlasH_Common.h

Define Documentation

RealParameter

Define RealParameterType

- Defined in file_SPlisHSPlasH_Common.h

Define Documentation

RealParameterType

Define RealVectorParameter

- Defined in file_SPlisHSPlasH_Common.h

Define Documentation

RealVectorParameter

Define RealVectorParameterType

- Defined in file_SPlisHSPlasH_Common.h

Define Documentation

RealVectorParameterType

Define REPORT_MEMORY_LEAKS

- Defined in file_SPlisHSPlasH_Common.h

Define Documentation**REPORT_MEMORY_LEAKS****Define USE_BLOCKDIAGONAL_PRECONDITIONER**

- Defined in file_SPlisHSPlasH_Viscosity_Viscosity_Weiler2018.h

Define Documentation**USE_BLOCKDIAGONAL_PRECONDITIONER****Define USE_WARMSTART**

- Defined in file_SPlisHSPlasH_DFSPH_TimeStepDFSPH.h

Define Documentation**USE_WARMSTART****Define USE_WARMSTART_V**

- Defined in file_SPlisHSPlasH_DFSPH_TimeStepDFSPH.h

Define Documentation**USE_WARMSTART_V****Define Vec3Block**

- Defined in file_SPlisHSPlasH_PF_TimeStepPF.cpp

Define Documentation

Warning: doxygen define: Cannot find define “Vec3Block” in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxyoutput/xml

6.3.7 Typedefs

Typedef AlignedBox2r

- Defined in file_SPlisHSPlasH_Common.h

Typedef Documentation

```
using AlignedBox2r = Eigen::AlignedBox<Real, 2>;
```

Typedef AlignedBox3r

- Defined in file_SPlisHSPlasH_Common.h

Typedef Documentation

```
using AlignedBox3r = Eigen::AlignedBox<Real, 3>;
```

Typedef AngleAxisr

- Defined in file_SPlisHSPlasH_Common.h

Typedef Documentation

```
using AngleAxisr = Eigen::AngleAxis<Real>;
```

Typedef AtomicRealVec

- Defined in file_SPlisHSPlasH_PF_TimeStepPF.cpp

Typedef Documentation

Warning: doxygen typedef: Cannot find typedef “AtomicRealVec” in doxygen xml output for project “SPlisHSPlasH” from directory: ./doxyoutput/xml

Typedef Matrix2r

- Defined in file_SPlisHSPlasH_Common.h

Typedef Documentation

```
using Matrix2r = Eigen::Matrix<Real, 2, 2, Eigen::DontAlign>
```

Typedef Matrix3f

- Defined in file_SPlisHSPlasH_Common.h

Typedef Documentation

```
using Matrix3f = Eigen::Matrix<float, 3, 3, Eigen::DontAlign>
```

Typedef Matrix3r

- Defined in file_SPlisHSPlasH_Common.h

Typedef Documentation

```
using Matrix3r = Eigen::Matrix<Real, 3, 3, Eigen::DontAlign>
```

Typedef Matrix4r

- Defined in file_SPlisHSPlasH_Common.h

Typedef Documentation

```
using Matrix4r = Eigen::Matrix<Real, 4, 4, Eigen::DontAlign>
```

Typedef Matrix5r

- Defined in file_SPlisHSPlasH_Common.h

Typedef Documentation

```
using Matrix5r = Eigen::Matrix<Real, 5, 5, Eigen::DontAlign>
```

Typedef Matrix6r

- Defined in file_SPlisHSPlasH_Common.h

Typeface Documentation

```
using Matrix6r = Eigen::Matrix<Real, 6, 6, Eigen::DontAlign>
```

Typeface NeighborhoodSearch

- Defined in file_SPlisHSPlasH_NeighborhoodSearch.h

Typeface Documentation

```
typedef CompactNSearch::NeighborhoodSearch NeighborhoodSearch
```

Typeface Quaternionr

- Defined in file_SPlisHSPlasH_Common.h

Typeface Documentation

```
using Quaternionr = Eigen::Quaternion<Real, Eigen::DontAlign>
```

Typeface Real

- Defined in file_SPlisHSPlasH_Common.h

Typeface Documentation

```
typedef float Real
```

Typeface SystemMatrixType

- Defined in file_SPlisHSPlasH_Utils_MatrixFreeSolver.h

Typeface Documentation

```
using SystemMatrixType = Eigen::SparseMatrix<Real>
```

Typeface Vector2i

- Defined in file_SPlisHSPlasH_Common.h

Typedef Documentation

```
using Vector2i = Eigen::Matrix<int, 2, 1, Eigen::DontAlign>
```

Typedef Vector2r

- Defined in file_SPlisHSPlasH_Common.h

Typedef Documentation

```
using Vector2r = Eigen::Matrix<Real, 2, 1, Eigen::DontAlign>
```

Typedef Vector3f

- Defined in file_SPlisHSPlasH_Common.h

Typedef Documentation

```
using Vector3f = Eigen::Matrix<float, 3, 1, Eigen::DontAlign>
```

Typedef Vector3r

- Defined in file_SPlisHSPlasH_Common.h

Typedef Documentation

```
using Vector3r = Eigen::Matrix<Real, 3, 1, Eigen::DontAlign>
```

Typedef Vector4f

- Defined in file_SPlisHSPlasH_Common.h

Typedef Documentation

```
using Vector4f = Eigen::Matrix<float, 4, 1, Eigen::DontAlign>
```

Typedef Vector4r

- Defined in file_SPlisHSPlasH_Common.h

Typedef Documentation

```
using Vector4r = Eigen::Matrix<Real, 4, 1, Eigen::DontAlign>
```

Typedef Vector5r

- Defined in file_SPlisHSPlasH_Common.h

Typedef Documentation

```
using Vector5r = Eigen::Matrix<Real, 5, 1, Eigen::DontAlign>
```

Typedef Vector6r

- Defined in file_SPlisHSPlasH_Common.h

Typedef Documentation

```
using Vector6r = Eigen::Matrix<Real, 6, 1, Eigen::DontAlign>
```

Typedef VectorXr

- Defined in file_SPlisHSPlasH_Common.h

Typedef Documentation

```
using SPH::TimeStepPF::VectorXr = Eigen::Matrix<Real, -1, 1>
```

CHAPTER
SEVEN

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